

# Phys 507 Recitation Sessions

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Fall, 2017

November 9, 2017 **Problem 8**

Sakurai's, 2.23.

## Problem 1

Sakurai's, 1.4.c.

## Problem 9

Sakurai's, 2.10.

## Problem 2

Sakurai's, 1.24.

November 23, 2017

## Problem 3

Sakurai's, 1.33.

## Problem 10

Sakurai's, 2.16.

## Problem 4<sup>1</sup>

Consider a quantum mechanical system which is described by a two dimensional Hilbert space spanned by basis vectors denoted  $|1\rangle$  and  $|2\rangle$ . Let us introduce an operator  $A$  whose matrix elements in this basis are

$$\langle 1|A|1\rangle = \langle 2|A|2\rangle = a$$

$$\langle 1|A|2\rangle = \langle 2|A|1\rangle = b$$

- (a) Find the eigenvectors and eigenvalues of  $A$ .
- (b) Suppose the system is in the state

$$|\alpha\rangle = \frac{1}{\sqrt{2}}|1\rangle + \frac{i}{\sqrt{2}}|2\rangle$$

What is the probability that when  $A$  is measured the result is  $a$ ?  $b$ ?  $a + b$ ?  $a - b$ ?

- (c) Compute  $\langle \Delta A^2 \rangle$  for this state.

## Problem 11

Sakurai's, 2.25.

## Problem 12

Sakurai's, 2.28.a.

## Problem 13

Sakurai's, 2.30.

December 7, 2017

## Problem 14

Sakurai's, 2.22.

## Problem 5<sup>2</sup>

A brief review of Stern-Gerlach experiment.

## Problem 15

Sakurai's, 2.27.

## Problem 16

November 16, 2017 Sakurai's, 2.32.

## Problem 6

Sakurai's, 1.28.

## Problem 7

Sakurai's, 2.6.

<sup>1</sup>Here, *Midterm 1, Problem 1.*

<sup>2</sup>Here, pp. 64-69.

## 1 Extra 1

1

Find the representation of the position operator in the momentum space. Solve the Schrödinger equation in the momentum space under the potential  $V(x) = -eEx$ .

## 2 Extra 2 : Sakurai 2.16, 17, 20, 39

## 3 Extra 3

The coherent states of the simple harmonic oscillator (SHO) are defined as the eigenkets of the annihilation operator,  $a|\lambda\rangle = \lambda|\lambda\rangle$ .

(a) Show that

$$|\lambda\rangle = \Delta(\lambda)|0\rangle \quad (3.1)$$

where  $|0\rangle$  is the ground state of the SHO and the *displacement* operator,  $\Delta(\lambda)$ , is defined as

$$\Delta(\lambda) := e^{\lambda a^\dagger - \lambda^* a} \quad (3.2)$$

(b) Show that  $Me^L M^{-1} = e^{MLM^{-1}}$  for any linear operators  $L$  and  $M$ . Compute  $U_0(t)^\dagger \Delta(\lambda) U_0(t)$  where  $U_0(t)$  is the usual time-evolution operator,  $U_0(t) = e^{-iH_0 t/\hbar}$ , and  $H_0$  is the SHO Hamiltonian,  $H_0 = P^2/2m + m\omega_0^2 X^2/2$ . By using the result, obtain the state ket at a later time,  $|\alpha, t_0 = 0; t\rangle$ , assuming the state is initially in one of the coherent states,  $|\alpha, t_0 = 0\rangle = |\lambda_0\rangle$ .

(c) Now suppose that there appears a constant external force,  $f$ , which produces an interaction term,  $H_1 = -fX$ . Obtain the second-order ordinary differential equation that the position operator,  $X$ , satisfies.

(d) In quantum mechanics, in addition to the Schrödinger and Heisenberg pictures, there is another one, called the *Dirac* (or *interaction*) picture. In this framework, both states and operators are evolving in time.

We define an *intermediate* state ket, say  $\alpha_I$ , via  $|\alpha, t_0 = 0; t\rangle = e^{-iH_0 t/\hbar} |\alpha_I, t_0 = 0; t\rangle$ . Noting that the total Hamiltonian now becomes  $H = H_0 + H_1$ , show that it satisfies the Schrödinger equation

$$i\hbar \frac{\partial}{\partial t} |\alpha_I, t_0 = 0; t\rangle = H_I(t) |\alpha_I, t_0 = 0; t\rangle \quad (3.3)$$

where  $H_I(t) := e^{iH_0 t/\hbar} H_1 e^{-iH_0 t/\hbar}$ . Since the interaction Hamiltonian,  $H_1$ , is a linear function of the position operator,  $X$ , we expect to have  $H_I(t) = g(t)^* a + g(t) a^\dagger$ . By using the Baker-Campbell-Hausdorff formula, obtain  $g(t)$ .

(e) From (3.3), we can deduce that there exists an *intermediate* time-evolution operator,  $U_I(t)$ , that satisfies

$$i\hbar \frac{\partial}{\partial t} U_I(t) = H_I(t) U_I(t) \quad (3.4)$$

By using the ansatz  $U_I(t) = e^{h(t)a^\dagger - h(t)^* a} e^{i\beta(t)}$ , derive the equations that  $h(t)$  and  $\beta(t)$  satisfy. Note that  $\beta(t)$  is a real-valued function.

(f) The motivation in employing the Dirac picture is that we partition a given Hamiltonian so that we have the complete solutions to one part, and we treat the rest as a *perturbation*.

Assuming that the intermediate state ket is initially in one of the coherent states,  $|\alpha_I, t_0 = 0\rangle = |\lambda_0\rangle$ , first obtain  $|\alpha_I, t_0 = 0; t\rangle$  by acting the *intermediate* time-evolution operator,  $U_I(t)$ , on this initial state. By using the result, find the final state ket by evolving it further with the usual time-evolution operator,  $U_0(t)$ . Demonstrate that the final state is of the form  $|\alpha, t_0 = 0; t\rangle = e^{i\gamma(t)} |\lambda(t)\rangle$  where  $\gamma$  is some time-dependent phase. Express  $\lambda(t)$  in terms of  $\lambda_0$ ,  $h(t)$ , and any other parameters relevant to the problem.

(g) Obtain the function  $h(t)$ . Use it to explicitly compute  $\lambda(t)$ . Letting  $x(t) := \sqrt{2\hbar/m\omega_0} \operatorname{Re} \lambda(t)$ , discuss whether it solves the equation of motion for the position operator you obtained in part (b).

## 4 Extra 4

2

Consider the Hamiltonian

$$H = \frac{L^2}{2I}$$

Describe the eigenvalues and the eigenfunctions. Discuss the degeneracy. What happens if we modify the Hamiltonian into

$$H' = \frac{L_x^2 + L_y^2}{2I_1} + \frac{L_z^2}{2I_2}$$

## 5 Extra 5 : Sakurai 3.5, 14, 15, 17, 18

## 6 Extra 6

3

Given  $|R, j\rangle = D_z^j(R) |j, j\rangle$  where  $D_z^j(R) = e^{iJ_3 \varphi/\hbar}$ , evaluate  $J_3 |R, j\rangle$ . What are the Euler angles of the operator  $D^j(R)$  that satisfies  $D^j(R) J_3 D^j(R)^{-1} = \vec{J} \cdot \hat{n}$ . Finally, show that  $\vec{J} \cdot \hat{n} |R, j\rangle = j |R, j\rangle$ .

<sup>1</sup>S. Kurkcuoglu, “Phys 507 Homework 2,” Nov. 2017.

<sup>2</sup>S. Kurkcuoglu, “Phys 507 Homework 3,” Dec. 2017.

<sup>3</sup>S. Kurkcuoglu, “Phys 507 Homework 3,” Dec. 2017.

①

## 507 RECIT 1

Sakurai, 1.4.c

Consider the most general form: w/  $A = A^\dagger$  and  $A|n\rangle = a_n|n\rangle$ ,

$$f(A) = \sum_j c_j A^j$$

$$A = \sum_n a_n |n\rangle \langle n|$$

$$A^2 = \sum_{nm} a_n a_m |n\rangle \underbrace{\langle n|m\rangle}_{\delta_{nm}} \langle m| = \sum_n a_n^2 |n\rangle \langle n|$$

...

$$A^j = \sum_n a_n^j |n\rangle \langle n|$$

$$\therefore f(A) = \sum_j c_j \sum_n a_n^j |n\rangle \langle n|$$

$$= \sum_n \left( \sum_j c_j a_n^j \right) |n\rangle \langle n|$$

$$= \sum_n f(a_n) |n\rangle \langle n|$$

$$\therefore e^{if(A)} = \sum_n e^{if(a_n)} |n\rangle \langle n|$$

$$\text{e.g. } e^{-iHt} = \sum_n e^{-iE_n t} |n\rangle \langle n| \quad \text{w/ } H|n\rangle = E_n|n\rangle$$

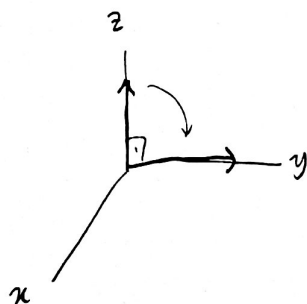
(2)

Sakurai 1.24

$$(a) \quad A := \frac{1}{\sqrt{2}} (1 + i\sigma_x) = \frac{1}{\sqrt{2}} \left( 1 + i \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix} \right) = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix}$$

let us apply it on something we know:

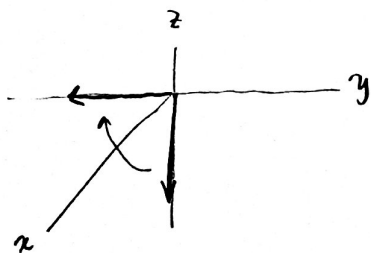
$$A|+\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix} = |y+\rangle$$



$$A|-\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} i \\ 1 \end{pmatrix}$$

$$= \frac{i}{\sqrt{2}} \begin{pmatrix} 1 \\ -i \end{pmatrix} = i|y-\rangle = e^{i\pi/2} |y-\rangle$$

phase  $\therefore$  no phys. sig.



$\therefore$  This is a rotator about the  $x$  by  $90^\circ$  cw.

$$(b) \quad S_z \doteq \begin{pmatrix} \langle y+ | S_z | y+ \rangle & \langle y+ | S_z | y- \rangle \\ \langle y- | S_z | y+ \rangle & \langle y- | S_z | y- \rangle \end{pmatrix}$$

Method 1: Use  $A$  above.

$$|y+\rangle = A|+\rangle$$

$$|y-\rangle = -iA|-\rangle$$



③

$$\langle y+ | S_z | y+ \rangle = \langle + | A^\dagger S_z A | + \rangle$$

$$\langle y+ | S_z | y- \rangle = -i \langle + | A^\dagger S_z A | - \rangle$$

$$\langle y- | S_z | y+ \rangle = i \langle - | A^\dagger S_z A | + \rangle$$

$$\langle y- | S_z | y- \rangle = \langle - | A^\dagger S_z A | - \rangle$$

$$A^\dagger S_z A = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & -i \\ -i & 1 \end{pmatrix} \frac{1}{2} \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & i \\ i & 1 \end{pmatrix}$$

$$= \frac{1}{4} \begin{pmatrix} 1 & -i \\ -i & 1 \end{pmatrix} \begin{pmatrix} 1 & i \\ -i & -1 \end{pmatrix}$$

$$= \frac{1}{4} \begin{pmatrix} 1-1 & 2i \\ -2i & 1-1 \end{pmatrix}$$

$$= \frac{1}{2} \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix}$$

$$\therefore \langle y+ | S_z | y+ \rangle = (1 \ 0) \frac{1}{2} \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = 0$$

$$\langle y+ | S_z | y- \rangle = -i (1 \ 0) \frac{1}{2} \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = \frac{1}{2}$$

$$\langle y- | S_z | y+ \rangle = i (0 \ 1) \frac{1}{2} \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix} \begin{pmatrix} 1 \\ 0 \end{pmatrix} = \frac{1}{2}$$

$$\langle y- | S_z | y- \rangle = (0 \ 1) \frac{1}{2} \begin{pmatrix} 0 & i \\ -i & 0 \end{pmatrix} \begin{pmatrix} 0 \\ 1 \end{pmatrix} = 0$$

$$\therefore S_z = \begin{pmatrix} 0 & 1/2 \\ 1/2 & 0 \end{pmatrix} = \frac{1}{2} \sigma_x$$

• Method 2

$$|y\pm\rangle = \frac{|+\rangle \pm i|-\rangle}{\sqrt{2}} \Rightarrow |+\rangle = \frac{|y+\rangle + |y-\rangle}{\sqrt{2}}, \quad |-\rangle = \frac{|y+\rangle - |y-\rangle}{\sqrt{2}i}$$

$$S_z = \frac{1}{2} (|+\rangle\langle+| - |-\rangle\langle-|) = \dots = \frac{1}{2} (|y+\rangle\langle y-| + |y-\rangle\langle y+|)$$

Then evaluate the matrix elements.

(4)

Sakurai 1.33

$$\begin{aligned}
\text{(a) i. } \langle p | \hat{x} | \alpha \rangle &= \langle p | \hat{x} \int dx | x \rangle \langle x | \alpha \rangle \\
&= \int dx \langle p | \hat{x} | x \rangle \langle x | \alpha \rangle \\
&= \int dx x \langle p | x \rangle \langle x | \alpha \rangle \\
&= \int dx dp' x \underbrace{\langle p | x \rangle}_{\frac{e^{-ipx}}{\sqrt{2\pi}}} \underbrace{\langle x | p' \rangle}_{\frac{e^{ip'x}}{\sqrt{2\pi}}} \langle p' | \alpha \rangle \\
&= \frac{1}{2\pi} \int dx dp' x e^{i(p'-p)x} \langle p' | \alpha \rangle \\
&= \frac{1}{2\pi} \int dx dp' \left( -\frac{1}{i} \frac{\partial}{\partial p} e^{i(p'-p)x} \right) \langle p' | \alpha \rangle \\
&= -\frac{1}{i} \frac{\partial}{\partial p} \int dp' \underbrace{\left( \int \frac{dx}{2\pi} e^{i(p'-p)x} \right)}_{\delta(p'-p)} \langle p' | \alpha \rangle \\
&= -\frac{1}{i} \frac{\partial}{\partial p} \langle p | \alpha \rangle \quad \text{qed}
\end{aligned}$$

$\therefore \hat{x} \rightarrow -\frac{1}{i} \frac{\partial}{\partial p}$  in momentum space

$$\begin{aligned}
\text{ii. } \langle \beta | \hat{x} | \alpha \rangle &= \int dp dp' \langle \beta | p \rangle \underbrace{\langle p | \hat{x} | p' \rangle}_{-\frac{1}{i} \frac{\partial}{\partial p} \underbrace{\langle p | p' \rangle}_{\delta(p-p')}} \langle p' | \alpha \rangle \\
&= -\frac{1}{i} \int dp dp' \langle \beta | p \rangle \frac{\partial}{\partial p} \delta(p-p') \langle p' | \alpha \rangle \\
&= -\frac{1}{i} \int dp \langle \beta | p \rangle \frac{\partial}{\partial p} \underbrace{\int dp' \delta(p-p') \langle p' | \alpha \rangle}_{\langle p | \alpha \rangle}
\end{aligned}$$

(5)

$$= -\frac{1}{i} \int dp \langle \beta | p \rangle \frac{\partial}{\partial p} \langle p | \alpha \rangle$$

$$= \int dp \psi_{\beta}(p)^* \frac{1}{i} \frac{\partial}{\partial p} \psi_{\alpha}(p) \quad \text{qed}$$

(b)  $T(x) = e^{-ipx}$  translation in space, generated by linear momentum.

$U(p) := e^{iXp}$  translation in momentum?

$$T(x) = \int dp e^{-ipx} |p\rangle \langle p|$$

$$T(a)|x\rangle = \int dp e^{-ipa} |p\rangle \langle p|x\rangle$$

$$= \int dx' dp e^{-ipa} \frac{e^{-ipx}}{\sqrt{2\pi}} |x'\rangle \langle x'|p\rangle$$

$$= \int dx' dp e^{-ipa} \frac{e^{-ipx}}{\sqrt{2\pi}} \frac{e^{ipx'}}{\sqrt{2\pi}} |x'\rangle$$

$$= \int dx' dp \frac{e^{ip(x'-(x+a))}}{2\pi} |x'\rangle$$

$$= \int dx' \left( \underbrace{\int dp \frac{e^{ip(x'-(x+a))}}{2\pi}}_{\delta(x'-(x+a))} \right) |x'\rangle$$

$$= |x+a\rangle$$

Similar,

$$U(p) = \int dx e^{ixp} |x\rangle \langle x|$$

$$U(k)|p\rangle = \int dx e^{ikx} |x\rangle \langle x|p\rangle$$

$$= \int dx dp' e^{ikx} |p'\rangle \langle p'|x\rangle \langle x|p\rangle$$

$$= \int dx dp' e^{ikx} |p'\rangle \frac{e^{-ip'x}}{\sqrt{2\pi}} \frac{e^{ipx}}{\sqrt{2\pi}}$$

⑥

$$\begin{aligned}
 &= \int dp' \left( \int dx \frac{e^{i x (p+k-p')}}{2\pi} \right) |p'\rangle \\
 &= \int dp' \delta(p' - (p+k)) |p'\rangle \\
 &= |p+k\rangle \quad \checkmark
 \end{aligned}$$

So it is indeed the translation operator in the momentum space.

#### Problem 4

$$\langle 1|A|1\rangle = \langle 2|A|2\rangle = a \Rightarrow A \supset a|1\rangle\langle 1| + a|2\rangle\langle 2|$$

$$\langle 1|A|2\rangle = \langle 2|A|1\rangle = b \Rightarrow A \supset b|1\rangle\langle 2| + b|2\rangle\langle 1|$$

$$|1\rangle \doteq \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad |2\rangle \doteq \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\therefore A = \begin{pmatrix} a & b \\ b & a \end{pmatrix}$$

(a)  $|A - \lambda| = 0$

$$\begin{vmatrix} a-\lambda & b \\ b & a-\lambda \end{vmatrix} = (a-\lambda)^2 - b^2 = 0 \Rightarrow \boxed{\lambda = a \pm b}$$

$$(A - \lambda)|\psi\rangle = 0$$

$$|\psi\rangle \doteq \begin{pmatrix} c_1 \\ c_2 \end{pmatrix}$$

$$\begin{pmatrix} a-\lambda & b \\ b & a-\lambda \end{pmatrix} \begin{pmatrix} c_1 \\ c_2 \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$(a-\lambda)c_1 + b c_2 = 0$$

$$c_2 = \frac{\lambda-a}{b} c_1 = \frac{a \pm b - a}{b} c_1 = \pm c_1 \quad \therefore \boxed{|\psi_{\pm}\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm 1 \end{pmatrix}}$$

(7)

$$(b) \quad |\alpha\rangle = \frac{1}{\sqrt{2}} (|1\rangle + i|2\rangle)$$

$$\boxed{P(a) = 0} \quad \text{: no such value in the spectrum of } A.$$

$$\boxed{P(b) = 0} \quad \text{simile}$$

To see this,

$$A|\psi'\rangle = a|\psi'\rangle$$

If  $|\psi'\rangle$  exists, we should be able to construct it:

$$|\psi'\rangle = \gamma_1 |1\rangle + \gamma_2 |2\rangle$$

$$A|\psi'\rangle = \gamma_1 (a+b) + \gamma_2 (a-b)|2\rangle = a\gamma_1 |1\rangle + a\gamma_2 |2\rangle$$

Since  $|1\rangle$  and  $|2\rangle$  are lin. indep,

$$\gamma_1 (a+b) = a\gamma_1 \Rightarrow \gamma_1 = 0$$

$$\gamma_2 (a-b) = a\gamma_2 \Rightarrow \gamma_2 = 0$$

So  $|\psi'\rangle$  is a trivial state:

$$|\psi'\rangle = 0$$

Then

$$P(a) = |\langle\psi'|\alpha\rangle|^2 = 0 \quad \text{trivially.}$$

$$P(a \pm b) = |\langle\psi_{\pm}|\alpha\rangle|^2$$

$$= \left| \frac{\langle 1 | \pm \langle 2 |}{\sqrt{2}} \frac{|1\rangle + i|2\rangle}{\sqrt{2}} \right|^2$$

$$= \frac{1}{4} |1 \pm i|^2$$

$$\boxed{P(a \pm b) = \frac{1}{2}}$$

(8)

$$(c) \quad A = \begin{pmatrix} a & b \\ b & a \end{pmatrix}$$

$$|\alpha\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix}$$

$$\langle A \rangle = \langle \alpha | A | \alpha \rangle = \frac{1}{\sqrt{2}} (1 \quad -i) \begin{pmatrix} a & b \\ b & a \end{pmatrix} \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix} = a$$

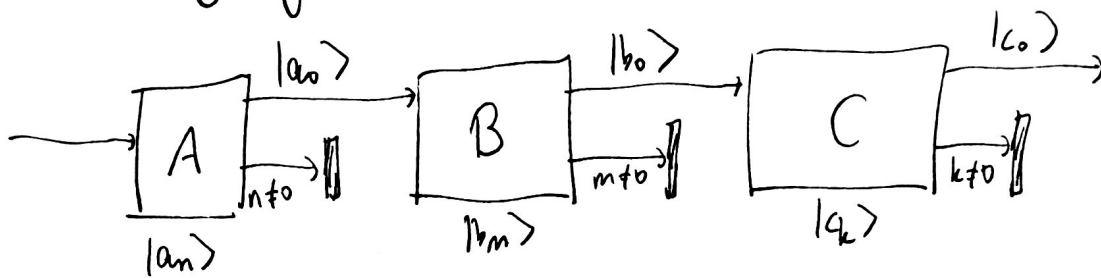
$$\langle A^2 \rangle = \langle \alpha | A^2 | \alpha \rangle = \frac{1}{\sqrt{2}} (1 \quad -i) \begin{pmatrix} a & b \\ b & a \end{pmatrix}^2 \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ i \end{pmatrix} = a^2 + b^2$$

$$\therefore \langle \Delta A^2 \rangle = \langle A^2 \rangle - \langle A \rangle^2 = a^2 + b^2 - a^2$$

$$\boxed{\langle \Delta A^2 \rangle = b^2}$$

Extra 1

## Philosophy of Measurement in QM



$T$ : transition amplitude (or probability amp.)

$$T = \langle \psi_f | \underbrace{Q}_{\text{any observable}} | \psi_i \rangle$$

Case 1 Measure and record  $b_0$  only:

$$T = \langle c_0 | b_0 \rangle \langle b_0 | a_0 \rangle$$

Final we force the initial  
B measurement  
to return  $b_0$  only  
 $\therefore$  we 'project'  $a_0$  on  $b_0$ .

In terms of Feynman's notation:

$$\underbrace{\langle \psi_f }_{\text{final state}} | \underbrace{\text{operation}}_{\text{a sequence of observations/operations}} | \underbrace{\psi_i \rangle}_{\text{initial state}}$$

Extra 2

Here, in this case,

$$\text{operation} = \hat{A}_0^B = |b_0\rangle\langle b_0|$$

↙  
projection operator for B kets

$$\text{So probability} = |T|^2$$

$$= |\langle c_0 | b_0 \rangle \langle b_0 | a_0 \rangle|^2$$

$$= |\langle c_0 | b_0 \rangle|^2 |\langle b_0 | a_0 \rangle|^2$$

Case 2 Measure and record all possible  $b_0$ 's.

$$|T|^2 = \sum_{b_0} |\langle c_0 | b_0 \rangle|^2 |\langle b_0 | a_0 \rangle|^2$$

Notice: We do not start from the amplitude:

$$T = \sum_{b_0} \langle c_0 | b_0 \rangle \langle b_0 | a_0 \rangle$$

$\therefore$  this ~~may~~ would mean that the 'transition' from  $a_0$  to  $c_0$  is indeed over all  $b_0$ 's — that's not the case here. But we want the total ~~probability~~



### Extra 3

'probability' if we consider all possible 'paths'. Recall we measure only the probability. So

$$|T|^2 = \sum_{b_0} |\langle c_0 | b_0 \rangle|^2 |\langle b_0 | a_0 \rangle|^2 \quad (*)$$

is indeed the result.

• Case 3 Do not measure or record any information coming out of B apparatus.

Now we have the following:

$$\begin{aligned} T &= \langle c_0 | b_0 \rangle \langle b_0 | a_0 \rangle \\ &+ \langle c_0 | b_1 \rangle \langle b_1 | a_0 \rangle \\ &+ \dots \\ &+ \langle c_0 | b_\infty \rangle \langle b_\infty | a_0 \rangle \end{aligned}$$

$$= \sum_{b_0} \langle c_0 | b_0 \rangle \langle b_0 | a_0 \rangle$$

So that's why we sum over the intermediate states at the beginning.

extra 4

probability here is

$$|T|^2 = \left| \sum_{b_0} \langle c_0 | b_0 \rangle \langle b_0 | a_0 \rangle \right|^2$$

$$= \sum_{b_0 b'_0} \langle c_0 | b_0 \rangle \langle b_0 | a_0 \rangle \langle a_0 | b'_0 \rangle \langle b'_0 | c_0 \rangle$$

which is most definitely not equal to (\*).

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Quote of the week:

"When in doubt, expand in a power series."

- Fermi

① 507 RECIT 2

Natural units:  $\hbar = c = 1$

Sakurai 1.28

$$(a) \quad [x, F(p)]_d = \frac{\partial x}{\partial x} \frac{\partial F(p)}{\partial p} - \cancel{\frac{\partial x}{\partial p} \frac{\partial F(p)}{\partial x}}_0$$

$$= \frac{\partial F(p)}{\partial p}$$

$$(b) \quad [X, e^{iPa}] = ?$$

• Method 1: Refer to the previous notes to see that

$$X \rightarrow -\frac{1}{i} \frac{\partial}{\partial p}$$

in momentum space:

$$\begin{aligned} [X, e^{iPa}] &= X e^{iPa} - e^{iPa} X \\ &= -\frac{1}{i} \frac{\partial}{\partial p} (e^{iPa}) - e^{iPa} \frac{-1}{i} \frac{\partial}{\partial p} \\ &= -\frac{1}{i} \frac{\partial e^{iPa}}{\partial p} - \cancel{\frac{1}{i} e^{iPa} \frac{\partial}{\partial p}} + \cancel{\frac{1}{i} e^{iPa} \frac{\partial}{\partial p}} \\ &= i \frac{\partial e^{iPa}}{\partial p} \\ &= -a e^{iPa} \end{aligned}$$

②

Method 2: Expand the exponential in a power series.

$$\begin{aligned} [X, e^{iP_0}] &= [X, \sum_j c_j P^j] \\ &= \sum_j c_j [X, P^j] \end{aligned}$$

$$[X, P] = i$$

$$[X, P^2] = P[X, P] + [X, P]P = 2iP$$

$$[X, P^3] = P[X, P^2] + [X, P]P^2 = 3iP^2$$

...

$$[X, P^j] = j i P^{j-1} = i \frac{\partial P^j}{\partial P}$$

$$\therefore [X, e^{iP_0}] = \sum_j c_j i \frac{\partial P^j}{\partial P}$$

$$= i \frac{\partial}{\partial P} \sum_j c_j P^j$$

$$= i \frac{\partial}{\partial P} e^{iP_0}$$

$$= -a e^{iP_0}$$

$$\textcircled{3} \quad (c) \quad X(e^{iPa} |x\rangle) = (e^{iPa} X + \underbrace{[X, e^{iPa}]}_{-ae^{iPa}}) |x\rangle$$

$$= e^{iPa} X |x\rangle - a e^{iPa} |x\rangle$$

$$= (x-a)(e^{iPa} |x\rangle) \quad \text{qed}$$

④

Solusi 2.6

$$H = \frac{p^2}{2m} + V(x)$$

$$[H, x] = \left[ \frac{p^2}{2m} + V(x), x \right]$$

$\underbrace{\hspace{10em}}_{=0}$

$$= \frac{1}{2m} [p^2, x]$$

$$= \frac{1}{2m} \left( \underbrace{p[p, x]}_{-i} + \underbrace{[p, x]p}_{-i} \right)$$

$$= -\frac{i p}{m}$$

$$[[H, x], x] = \left[ -\frac{i p}{m}, x \right]$$

$$= -\frac{i}{m} \underbrace{[p, x]}_{-i}$$

$$= -\frac{1}{m}$$

$$[x, [H, x]] = \frac{1}{m}$$

⑤

$$\langle n | [X, [H, X]] | n \rangle = \langle n | [X, HX - XH] | n \rangle$$

$$= \langle n | XHX - X^2H - HX^2 + XHX | n \rangle$$

$$= 2 \langle n | XHX | n \rangle - \underbrace{\langle n | X^2H | n \rangle}_{E_n} - \underbrace{\langle n | HX^2 | n \rangle}_{E_n}$$

$$= 2 \left( \langle n | XHX | n \rangle - \langle n | X^2 | n \rangle E_n \right) \quad \text{⑥}$$

$$\langle n | XHX | n \rangle = \langle n | X \sum_m | m \rangle \langle m | H \sum_k | k \rangle \langle k | X | n \rangle$$

$$= \sum_{mk} \langle n | X | m \rangle \underbrace{\langle m | H | k \rangle}_{E_k \delta_{mk}} \langle k | X | n \rangle$$

$$= \sum_{mk} \langle n | X | m \rangle E_k \delta_{mk} \langle k | X | n \rangle$$

$$= \sum_m \langle n | X | m \rangle \langle m | X | n \rangle E_m$$

$$= \sum_m |\langle n | X | m \rangle|^2 E_m$$

$$\text{⑦ } 2 \left( \sum_m |\langle n | X | m \rangle|^2 E_m - \underbrace{\langle n | X^2 | n \rangle}_{= \langle n | XX | n \rangle} E_n \right)$$

$$= \langle n | X \sum_m | m \rangle \langle m | X | n \rangle$$

$$= \sum_m \langle n | X | m \rangle \langle m | X | n \rangle$$

$$= \sum_m |\langle n | X | m \rangle|^2$$

⑥

$$= 2 \left( \sum_m |\langle n | X | m \rangle|^2 E_m - \sum_m |\langle n | X | m \rangle|^2 E_n \right)$$

$$= 2 \sum_m |\langle n | X | m \rangle|^2 (E_m - E_n)$$

$$\langle n | [X, [H, X]] | n \rangle = \langle n | \frac{1}{m} | n \rangle = \frac{1}{m} \underbrace{\langle n | n \rangle}_1 = \frac{1}{m}$$

$$\therefore 2 \sum_m |\langle n | X | m \rangle|^2 (E_m - E_n) = \frac{1}{m}$$

$$\therefore \sum_m |\langle n | X | m \rangle|^2 (E_m - E_n) = \frac{1}{2m} \quad \text{qed}$$



⑦

Sakurai 2.23

$$V(x) = \begin{cases} 0, & 0 < x < L \\ \infty, & \text{o.w} \end{cases} \quad \text{"particle in a box"}$$

$$H|n\rangle = E_n|n\rangle$$

$$\langle x|n\rangle = \sqrt{\frac{2}{L}} \sin \frac{n\pi x}{L}, \quad n \in \mathbb{Z}^+ \quad \text{from elementary quantum mech.}$$

$$|\alpha(0)\rangle = \sum_{n \geq 1} |n\rangle \langle n|\alpha(0)\rangle$$

$$\langle x|\alpha(0)\rangle = \delta(x - \frac{L}{2})$$

$$\langle x|\alpha(t)\rangle = ?$$

$$|\alpha(t)\rangle = e^{-iHt} |\alpha(0)\rangle, \quad f(A) = \sum_n f(a_n) |a_n\rangle \langle a_n|$$

$$= \sum_{n \geq 1} e^{-iE_n t} |n\rangle \langle n|\alpha(0)\rangle$$

$$= \sum_{n \geq 1} e^{-iE_n t} |n\rangle \langle n| \int_0^L dx |x\rangle \langle x|\alpha(0)\rangle$$

$$= \sum_{n \geq 1} e^{-iE_n t} |n\rangle \int_0^L dx \underbrace{\langle n|x\rangle}_{= \langle x|n\rangle^*} \underbrace{\langle x|\alpha(0)\rangle}_{\delta(x - \frac{L}{2})}$$

$$= \sqrt{\frac{2}{L}} \sin \frac{n\pi x}{L}$$

⑧

$$= \sum_{n \geq 1} e^{-iE_n t} |n\rangle \int_0^L dx \sqrt{\frac{2}{L}} \sin \frac{n\pi x}{L} \delta(x - \frac{L}{2})$$

$$= \sum_{n \geq 1} e^{-iE_n t} |n\rangle \sqrt{\frac{2}{L}} \sin \frac{n\pi}{2}$$

$$\langle x | \alpha(t) \rangle = \sum_{n \geq 1} e^{-iE_n t} \underbrace{\langle x | n \rangle}_{\sqrt{\frac{2}{L}} \sin \frac{n\pi x}{L}} \sqrt{\frac{2}{L}} \sin \frac{n\pi}{2}$$

$$= \sum_{n \geq 1} e^{-iE_n t} \frac{2}{L} \sin \frac{n\pi}{2} \sin \frac{n\pi x}{L}$$

9)

Solunai 2.10

$$H = \Delta (|L\rangle\langle R| + |R\rangle\langle L|)$$

$$(a) \quad |L\rangle \doteq \begin{pmatrix} 1 \\ 0 \end{pmatrix}, \quad |R\rangle \doteq \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$\therefore H = \Delta \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix}$$

$$|H - \lambda| = 0$$

$$\begin{vmatrix} -\lambda & \Delta \\ \Delta & -\lambda \end{vmatrix} = \lambda^2 - \Delta^2 = 0 \Rightarrow \lambda = \pm \Delta$$

$$(H - \lambda)|\pm\rangle = 0, \quad |\pm\rangle \doteq \begin{pmatrix} a \\ b \end{pmatrix}$$

$$\begin{pmatrix} -\lambda & \Delta \\ \Delta & -\lambda \end{pmatrix} \begin{pmatrix} a \\ b \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \end{pmatrix}$$

$$-\lambda a + \Delta b = 0$$

$$b = \frac{\lambda}{\Delta} a = \begin{cases} a \\ -a \end{cases} = \pm a$$

$$\therefore |\pm\rangle = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 \\ \pm 1 \end{pmatrix} = \frac{|L\rangle \pm |R\rangle}{\sqrt{2}}$$

(10)

$$(b) \quad |\alpha(0)\rangle = |R\rangle \langle R|\alpha(0)\rangle + |L\rangle \langle L|\alpha(0)\rangle$$

$$= |R\rangle c_R(0) + |L\rangle c_L(0)$$

$$|\alpha(t)\rangle = e^{-iHt} |\alpha(0)\rangle$$

$$= e^{-iHt} \left( \underbrace{c_R(0)}_{\frac{|+\rangle - |-\rangle}{\sqrt{2}}} |R\rangle + \underbrace{c_L(0)}_{\frac{|+\rangle + |-\rangle}{\sqrt{2}}} |L\rangle \right)$$

$$= \frac{c_R(0)}{\sqrt{2}} \left( e^{-iHt} |+\rangle - e^{-iHt} |-\rangle \right) + \frac{c_L(0)}{\sqrt{2}} \left( e^{-iHt} |+\rangle + e^{-iHt} |-\rangle \right)$$

$$= \frac{c_R(0)}{\sqrt{2}} \left( e^{-i\Delta t} |+\rangle - e^{+i\Delta t} |-\rangle \right) + \frac{c_L(0)}{\sqrt{2}} \left( e^{-i\Delta t} |+\rangle + e^{+i\Delta t} |-\rangle \right)$$

$$= |+\rangle \frac{c_R(0) + c_L(0)}{\sqrt{2}} e^{-i\Delta t} + |-\rangle \frac{c_L(0) - c_R(0)}{\sqrt{2}} e^{+i\Delta t}$$

$$= \frac{|L\rangle + |R\rangle}{\sqrt{2}} \frac{c_R(0) + c_L(0)}{\sqrt{2}} e^{-i\Delta t} + \frac{|L\rangle - |R\rangle}{\sqrt{2}} \frac{c_L(0) - c_R(0)}{\sqrt{2}} e^{+i\Delta t}$$

$$= |L\rangle \left( -i \sin \Delta t c_R(0) + \cos \Delta t c_L(0) \right)$$

$$+ |R\rangle \left( \cos \Delta t c_R(0) - i \sin \Delta t c_L(0) \right)$$

(11)

$$|\alpha(t)\rangle = |L\rangle (-i \sin \Delta t c_R(0) + \cos \Delta t c_L(0)) \\ + |R\rangle (\cos \Delta t c_R(0) - i \sin \Delta t c_L(0))$$

$$(c) \quad |\alpha(0)\rangle = |R\rangle \Rightarrow c_L(0) = 0, c_R(0) = 1$$

$$\therefore |\alpha(t)\rangle = -i \sin \Delta t |L\rangle + \cos \Delta t |R\rangle$$

$$P(L) = |\langle L | \alpha(t) \rangle|^2$$

$$(d) \quad \psi = \begin{pmatrix} \langle L | \alpha(t) \rangle \\ \langle R | \alpha(t) \rangle \end{pmatrix} =: \begin{pmatrix} c_L(t) \\ c_R(t) \end{pmatrix}$$

$$= c_L(t) \begin{pmatrix} 1 \\ 0 \end{pmatrix} + c_R(t) \begin{pmatrix} 0 \\ 1 \end{pmatrix}$$

$$= c_L(t) |L\rangle + c_R(t) |R\rangle$$

$$i \frac{\partial \psi}{\partial t} = H \psi$$

Assume  $\exists U$  s.t.  $U^\dagger U = 1$  et  $U^\dagger H U = \begin{pmatrix} \Delta & \\ & -\Delta \end{pmatrix}$ .  
 From elementary algebra, one such matrix is

$$U = \begin{pmatrix} 1/\sqrt{2} & 1/\sqrt{2} \\ 1/\sqrt{2} & -1/\sqrt{2} \end{pmatrix} = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix}$$

$\uparrow \quad \quad \uparrow$   
 $|+\rangle \quad |-\rangle$

$$i \frac{\partial \psi}{\partial t} = H \psi = H U U^\dagger \psi \quad | \quad U^\dagger \rightarrow$$

$$i \frac{\partial}{\partial t} \underbrace{U^\dagger \psi}_{\tilde{\psi}} = \underbrace{U^\dagger H U}_{\begin{pmatrix} \Delta & \\ & -\Delta \end{pmatrix}} \underbrace{U^\dagger \psi}_{\tilde{\psi}}$$

$$=: E$$

$$i \frac{\partial \tilde{\psi}}{\partial t} = E \tilde{\psi}$$

$$\frac{\partial \tilde{\psi}}{\partial t} = -i E \tilde{\psi}$$

$$\frac{\partial \tilde{\psi}}{\tilde{\psi}} = -i E \partial t$$

$$\ln \tilde{\psi}(t) = -i E t + \ln \tilde{\psi}(0)$$

$$\tilde{\psi}(t) = \tilde{\psi}(0) e^{-i E t} \quad (*)$$

$$\tilde{\psi} = U^\dagger \psi = \frac{1}{\sqrt{2}} \begin{pmatrix} 1 & 1 \\ 1 & -1 \end{pmatrix} \begin{pmatrix} c_L(t) \\ c_R(t) \end{pmatrix}$$

$$= \begin{pmatrix} \frac{c_L(t) + c_R(t)}{\sqrt{2}} \\ \frac{c_L(t) - c_R(t)}{\sqrt{2}} \end{pmatrix}$$

(13)

$$(*) \begin{cases} \frac{c_L(t) + c_R(t)}{\sqrt{2}} = e^{-i\Delta t} \frac{c_L(0) + c_R(0)}{\sqrt{2}} \\ \frac{c_L(t) - c_R(t)}{\sqrt{2}} = e^{+i\Delta t} \frac{c_L(0) - c_R(0)}{\sqrt{2}} \end{cases}$$

$$c_L(t) = \frac{1}{2} \left( e^{-i\Delta t} (c_L(0) + c_R(0)) + e^{+i\Delta t} (c_L(0) - c_R(0)) \right)$$

$$= c_L(0) \cos \Delta t - i c_R(0) \sin \Delta t$$

$$c_R(t) = \frac{1}{2} \left( e^{-i\Delta t} (c_L(0) + c_R(0)) - e^{+i\Delta t} (c_L(0) - c_R(0)) \right)$$

$$= -i c_L(0) \sin \Delta t + c_R(0) \cos \Delta t$$

$$\therefore \psi = c_L(t) |L\rangle + c_R(t) |R\rangle$$

$$= (c_L(0) \cos \Delta t - i c_R(0) \sin \Delta t) |L\rangle$$

$$+ (-i c_L(0) \sin \Delta t + c_R(0) \cos \Delta t) |R\rangle$$

which is the same as in part (b).

(14)

$$(e) \quad \tilde{H} = \Delta |L\rangle\langle R|$$

$$\langle \alpha(t) | \alpha(t) \rangle \stackrel{?}{=} \langle \alpha(0) | \alpha(0) \rangle$$

$$\langle \alpha(0) | e^{i\tilde{H}^\dagger t} e^{-i\tilde{H}t} | \alpha(0) \rangle \stackrel{?}{=} \langle \alpha(0) | \alpha(0) \rangle$$

$$\underbrace{e^{i(\tilde{H}^\dagger - \tilde{H})t}}_{\neq 1 \because \tilde{H}^\dagger \neq \tilde{H}}$$

$$\therefore \langle \alpha(t) | \alpha(t) \rangle \neq \langle \alpha(0) | \alpha(0) \rangle$$

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Quote of the week:

"Whatever is not expressly forbidden is mandatory."

- Feynman



①

507 RECIT 3Sakurai, 2.16

$$C_n(t) := \langle n(t) | n(0) \rangle$$

$$\begin{aligned} x(t) &= U^\dagger x(0) U \\ &= e^{iHt} x e^{-iHt} \end{aligned}$$

$$C_n(t) = \langle n | e^{iHt} x e^{-iHt} | n \rangle$$

$$a_{\pm} := \frac{1}{\sqrt{2m\omega\hbar}} (m\omega x \mp ip) \quad (a \leftrightarrow a_-, a^\dagger \leftrightarrow a_+)$$

$$a_+ |n\rangle = \sqrt{n+1} |n+1\rangle, \quad a_- |n\rangle = \sqrt{n} |n-1\rangle$$

$$\sqrt{2m\omega\hbar} a_+ = m\omega x - ip$$

$$\sqrt{2m\omega\hbar} a_- = m\omega x + ip$$

$$x = \frac{1}{2m\omega} (\sqrt{2m\omega\hbar} a_+ + \sqrt{2m\omega\hbar} a_-)$$

$$= \sqrt{\frac{\hbar}{2m\omega}} (a_+ + a_-)$$

$$p = \frac{1}{2i} (-\sqrt{2m\omega\hbar} a_+ + \sqrt{2m\omega\hbar} a_-)$$

$$= i\sqrt{\frac{m\omega\hbar}{2}} (a_+ - a_-)$$

②

$$C_n(t) = \langle n | e^{iHt} \alpha e^{-iHt} | n \rangle$$

$$= \langle n | e^{iHt} \alpha e^{-iHt} \sum_m | m \rangle \langle m | \alpha | n \rangle$$

$$= \sum_m \underbrace{\langle n | e^{iHt} \alpha e^{-iHt} | m \rangle}_{e^{iE_n t}} \underbrace{\langle m | \alpha | n \rangle}_{e^{-iE_m t}}$$

$$= \sum_m e^{i(E_n - E_m)t} \cdot \langle n | \alpha | m \rangle \langle m | \alpha | n \rangle$$

$$= \sum_m e^{i(E_n - E_m)t} |\langle n | \alpha | m \rangle|^2$$

$$\langle n | \alpha | m \rangle = \sqrt{\frac{\hbar}{2m\omega}} \langle n | a_+ + a_- | m \rangle$$

$$= \sqrt{\frac{\hbar}{2m\omega}} \left( \langle n | a_+ | m \rangle + \langle n | a_- | m \rangle \right)$$

$$= \sqrt{\frac{\hbar}{2m\omega}} \left( \langle n | \sqrt{m+1} | m+1 \rangle + \langle n | \sqrt{m} | m-1 \rangle \right)$$

$$= \sqrt{\frac{\hbar}{2m\omega}} \left( \sqrt{m+1} \delta_{n,m+1} + \sqrt{m} \delta_{n,m-1} \right)$$

③

$$|\langle n | x | m \rangle|^2 = \frac{\hbar}{2m\omega} (\sqrt{m+1} \delta_{n,m+1} + \sqrt{m} \delta_{n,m-1})^2$$

$n=0$ :

$$C_0(t) = \sum_m e^{i(E_0 - E_m)t} \frac{\hbar}{2m\omega} (\sqrt{m+1} \delta_{0,m+1} + \sqrt{m} \delta_{0,m-1})^2$$

$$= \frac{\hbar}{2m\omega} \left( e^{i(E_0 - E_0)t} (\overbrace{\delta_{01} + 0}^0)^2 + e^{i(E_0 - E_1)t} (\underbrace{\sqrt{2} \delta_{02}}_0 + \underbrace{\delta_{00}}_1)^2 + e^{i(E_0 - E_2)t} (\sqrt{3} \delta_{03} + \sqrt{2} \delta_{01})^2 + \dots \right)$$

$$= \frac{\hbar}{2m\omega} e^{i(E_0 - E_1)t}$$

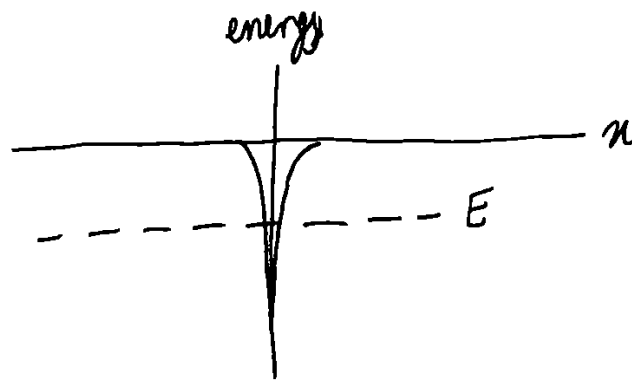
$$= \frac{\hbar}{2m\omega} e^{i \left( \frac{\hbar\omega}{2} - \frac{3\hbar\omega}{2} \right) t / \hbar}$$

$$\boxed{C_0(t) = \frac{\hbar}{2m\omega} e^{-i\omega t}}$$

④

Sakurai, 2.25

$V(x) = -\lambda \delta(x)$ ,  $\lambda > 0$ ,  $E < 0$ , bound states



$$H \phi_n(x) = E_n \phi_n(x)$$

$$-\frac{\hbar^2}{2m} \phi_n'' - \lambda \delta(x) \phi_n = E_n \phi_n = -|E_n| \phi_n$$

$x > 0$ :

$$-\frac{\hbar^2}{2m} \phi_n'' = -|E_n| \phi_n$$

$$\phi_n'' = \frac{2m|E_n|}{\hbar^2} \phi_n =: K^2 \phi_n$$

$$\phi_n(x) = A e^{-Kx} + B e^{Kx}$$

$x < 0$ : (symmetric)

$$\phi_n(x) = C e^{Kx}$$

5

~~scribbled out text~~

$$\phi_n(0^-) = \phi_n(0^+) \Rightarrow A = C$$

$\kappa = 0$ :

$$-\frac{\hbar^2}{2m} \phi_n'' - \lambda \delta(x) \phi_n = E_n \phi_n \quad \Big| \quad \int_{0^-}^{0^+} dx$$

$$-\frac{\hbar^2}{2m} (\phi_n'(0^+) - \phi_n'(0^-)) - \lambda \phi_n(0) = \text{scribbled out } 0$$

$$\phi_n'(0^+) - \phi_n'(0^-) = -\frac{2m\lambda}{\hbar^2} \phi_n(0)$$

$$-KA - KA = -\frac{2m\lambda}{\hbar^2} A$$

$$K = \frac{m\lambda}{\hbar^2}$$

$$K^2 = \frac{2m|E_n|}{\hbar^2} = \frac{m^2\lambda^2}{\hbar^4}$$

$$|E_n| = \frac{m\lambda^2}{2\hbar^2} \quad \text{only one state}$$

$$E = -\frac{m\lambda^2}{2\hbar^2}$$

⑥

$$\psi(x) = \begin{cases} Ae^{-Kx}, & x > 0 \\ Ae^{Kx}, & x < 0 \end{cases}$$

$$= Ae^{-K|x|}$$

$$\int_{-\infty}^{\infty} dx |\psi(x)|^2 = 1$$

$$A^2 \int_{-\infty}^{\infty} dx e^{-2K|x|} = 1$$

$$2A^2 \int_0^{\infty} dx e^{-2Kx} = 1$$

$$2A^2 \frac{1}{2K} = 1$$

$$A = \sqrt{K} = \sqrt{\frac{m\lambda}{\hbar^2}}$$

$$\psi(x) = \sqrt{K} e^{-K|x|}, \quad x < 0$$

$$\therefore \langle x | \alpha(0) \rangle = \sqrt{K} e^{-K|x|}$$

7)

$$\langle x | \alpha(t) \rangle = ?$$

$$H = \frac{p^2}{2m}, \quad t > 0$$

$$\langle x | \alpha(t) \rangle = \langle x | e^{-iHt/\hbar} | \alpha(0) \rangle$$

$$= \langle x | e^{-iP^2 t / 2m\hbar} | \alpha(0) \rangle$$

$$= \langle x | e^{-iP^2 t / 2m\hbar} \int dp |p\rangle \langle p| \int dx' |x'\rangle \langle x' | \alpha(0) \rangle$$

$$= \int dx' dp \underbrace{\langle x | e^{-iP^2 t / 2m\hbar} |p\rangle}_{e^{-ip^2 t / 2m\hbar}} \langle p | x' \rangle \langle x' | \alpha(0) \rangle$$

$$= \int dx' dp e^{-ip^2 t / 2m\hbar} \underbrace{\langle x | p \rangle \langle p | x' \rangle}_{\frac{e^{ip(x-x')/\hbar}}{2\pi\hbar}} \langle x' | \alpha(0) \rangle$$

$$= \int dx' dp \frac{e^{-ip^2 t / 2m\hbar + ip(x-x')/\hbar}}{2\pi\hbar} \langle x' | \alpha(0) \rangle$$

(8)

$$\int_{-\infty}^{\infty} dp \, e^{-i \left( \frac{t}{2m\hbar} p^2 - \frac{x-x'}{\hbar} p \right)} = ?$$

$$p^2 \rightarrow p^2 - i\varepsilon, \quad \varepsilon \sim 0$$

$$-i \left( \frac{t}{2m\hbar} (p^2 - i\varepsilon) - \frac{x-x'}{\hbar} p \right) = -i \left( \frac{t}{2m\hbar} p^2 - \frac{x-x'}{\hbar} p \right) - \varepsilon$$

$\varepsilon$  will regulate the integral so we can compute the usual Fresnel-Gauss integral:

$$\int_{-\infty}^{\infty} dp \, e^{- \left( \frac{it}{2m\hbar} p^2 - \frac{i(x-x')}{\hbar} p \right)} = ?$$

$$A := \frac{it}{2m\hbar}, \quad B := - \frac{i(x-x')}{\hbar}$$

$$Ap^2 + Bp = A p^2 + 2 \frac{B}{2\sqrt{A}} \sqrt{A} p + \frac{B^2}{4A} - \frac{B^2}{4A}$$

$$= \left( \sqrt{A} p + \frac{B}{2\sqrt{A}} \right)^2 - \frac{B^2}{4A}$$

$$= A \left( p + \frac{B}{2A} \right)^2 - \frac{B^2}{4A}$$

$$\int_{-\infty}^{\infty} dp \, e^{-(Ap^2 + Bp)} = \int_{-\infty}^{\infty} dp \, e^{-A(p + B/2A)^2} e^{-B^2/4A}, \quad p \rightarrow p - \frac{B}{2A}$$



9

$$= \int_{-\infty}^{\infty} dp e^{-Ap^2} e^{-B^2/4A}$$

$$= \sqrt{\frac{\pi}{A}} e^{-B^2/4A}$$

$$= \sqrt{\frac{\pi}{it/2m\hbar}} \exp \frac{\left(-\frac{i(x-x')}{\hbar}\right)^2}{4 \frac{it}{2m\hbar}}$$

$$= \sqrt{\frac{2m\hbar\pi}{it}} \exp \frac{-\frac{(x-x')^2}{\hbar^2}}{\frac{2it}{m\hbar}}$$

$$\underbrace{e^{i(x-x')^2 m/2\hbar t}}$$

$$= \sqrt{\frac{2m\hbar\pi}{it}} e^{i(x-x')^2 m/2\hbar t}$$

$$\langle x|\alpha(t)\rangle = \int \frac{1}{2\pi\hbar} \int_{-\infty}^{\infty} dx' \sqrt{\frac{2m\hbar\pi}{it}} e^{i(x-x')^2 m/2\hbar t} \langle x'|\alpha(0)\rangle$$

$$= \frac{m}{\sqrt{2\pi\hbar it}} \int_{-\infty}^{\infty} dx' e^{i(x-x')^2 m/2\hbar t} \sqrt{K} e^{-K|x|}$$

(10)

$$= \sqrt{\frac{Km}{2\pi\hbar it}} \left( \int_0^\infty dx' e^{i(x-x')^2 m/2\hbar t} e^{-Kx'} + \int_{-\infty}^0 dx' e^{i(x-x')^2 m/2\hbar t} e^{Kx'} \right) \rightarrow x' \rightarrow -x'$$

$$= \sqrt{\frac{Km}{2\pi\hbar it}} \left( \int_0^\infty dx' e^{i(x-x')^2 m/2\hbar t} e^{-Kx'} + \int_0^\infty dx' e^{i(x+x')^2 m/2\hbar t} e^{-Kx'} \right)$$

$$= \sqrt{\frac{Km}{2\pi\hbar it}} \left( \int_0^\infty dx' e^{-\frac{m}{2\hbar t} (x-x')^2 - Kx'} + \int_0^\infty dx' e^{-\frac{m}{2\hbar t} (x+x')^2 - Kx'} \right)$$

$$= \sqrt{\frac{Km}{2\pi\hbar it}} \left( \int_0^\infty dx' e^{-\left(\frac{m}{2\hbar t} (x-x')^2 + Kx'\right)} + \int_0^\infty dx' e^{-\left(\frac{m}{2\hbar t} (x+x')^2 + Kx'\right)} \right)$$

11)

$$\frac{m}{2i\hbar t} (x \pm x')^2 + Kx' = \frac{mx^2}{2i\hbar t} + \frac{m}{2i\hbar t} x'^2 \pm 2 \frac{m}{2i\hbar t} xx' + Kx'$$

$$= \frac{m}{2i\hbar t} x'^2 + \left( K \pm \frac{mx}{i\hbar t} \right) x' + \frac{mx^2}{2i\hbar t}$$

$$= C x'^2 + D_{\pm} x' + E$$

$$= C x'^2 + 2 \frac{D_{\pm}}{2\sqrt{C}} \sqrt{C} x' + \frac{D_{\pm}^2}{4C} - \frac{D_{\pm}^2}{4C} + E$$

$$= \left( \sqrt{C} x' + \frac{D_{\pm}}{2\sqrt{C}} \right)^2 + E - \frac{D_{\pm}^2}{4C}$$

$$= C \left( x' + \frac{D_{\pm}}{2C} \right)^2 + E - \frac{D_{\pm}^2}{4C}$$

$$\therefore \langle x | \alpha(t) \rangle = \sqrt{\frac{m}{2i\pi\hbar t}} \sqrt{\frac{Km}{2\pi\hbar t}}$$

$$\times \left( \int_0^{\infty} dx' e^{-C(x' + D_-/2C)^2} e^{-E + D_-^2/4C} \Rightarrow x' \rightarrow x' - \frac{D_-}{2C} \right.$$

$$\left. + \int_0^{\infty} dx' e^{-C(x' + D_+/2C)^2} e^{-E + D_+^2/4C} \right) \Rightarrow x' \rightarrow x' - \frac{D_+}{2C}$$

(12)

$$\begin{aligned}
&= \sqrt{\frac{Km^2}{(2\pi i\hbar t)^2}} \left( \int_{-D_-/2C}^{\infty} dx' e^{-Cx'^2} e^{-E+D_-^2/4C} \right. \\
&\quad \left. + \int_{-D_+/2C}^{\infty} dx' e^{-Cx'^2} e^{-E+D_+^2/4C} \right) \\
&= \sqrt{\frac{Km^2}{(2\pi i\hbar t)^2}} \left[ \left( \int_0^{\infty} dx' e^{-Cx'^2} + \int_{-D_-/2C}^0 dx' e^{-Cx'^2} \right) e^{-E+D_-^2/4C} \right. \\
&\quad \left. + \left( \int_0^{\infty} dx' e^{-Cx'^2} + \int_{-D_+/2C}^0 dx' e^{-Cx'^2} \right) e^{-E+D_+^2/4C} \right] \\
&= \frac{\sqrt{K} m}{2\pi i\hbar t} \left( e^{-E+D_-^2/4C} \frac{1}{2} \sqrt{\frac{\pi}{C}} + e^{-E+D_-^2/4C} \int_0^{D_-/2C} dx' e^{-Cx'^2} \right. \\
&\quad \left. + e^{-E+D_+^2/4C} \frac{1}{2} \sqrt{\frac{\pi}{C}} + e^{-E+D_+^2/4C} \int_0^{D_+/2C} dx' e^{-Cx'^2} \right) \\
&= \frac{\sqrt{K} m}{2\pi i\hbar t} \left( \frac{1}{2} \sqrt{\frac{\pi}{C}} \left( e^{-E+D_-^2/4C} + e^{-E+D_+^2/4C} \right) \right. \\
&\quad \left. + e^{-E+D_-^2/4C} \frac{1}{2} \sqrt{\frac{\pi}{C}} \operatorname{erf}\left(\frac{D_-}{2\sqrt{C}}\right) \right. \\
&\quad \left. + e^{-E+D_+^2/4C} \frac{1}{2} \sqrt{\frac{\pi}{C}} \operatorname{erf}\left(\frac{D_+}{2\sqrt{C}}\right) \right)
\end{aligned}$$

(13)

$$\therefore \langle x | \alpha(t) \rangle = \frac{\sqrt{K} \cdot m}{4\pi i \hbar t} \sqrt{\frac{\pi}{C}} \times \left( e^{-E + D_+^2/4C} \left( 1 + \operatorname{erf} \left( \frac{D_+}{2\sqrt{C}} \right) \right) + e^{-E + D_-^2/4C} \left( 1 + \operatorname{erf} \left( \frac{D_-}{2\sqrt{C}} \right) \right) \right)$$

where

$$K = \frac{m \lambda}{\hbar^2}$$

$$C = \frac{m}{2i\hbar t}$$

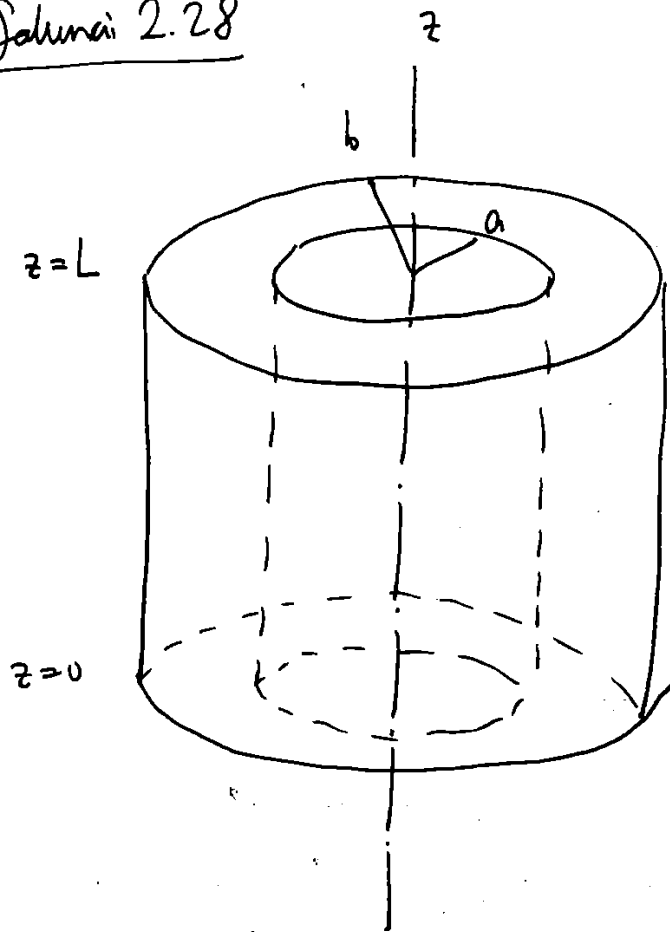
$$D_{\pm} = K \pm \frac{mx}{i\hbar t}$$

$$E = \frac{mx^2}{2i\hbar t}$$

$$\operatorname{erf}(x) := \frac{2}{\sqrt{\pi}} \int_0^x du e^{-u^2}$$

(14)

Sakurai 2.28



particle is ~~free~~ in the region

$$a < s < b$$

$$0 < z < L$$

$$0 < \phi < 2\pi$$

(15)

$$(a) \quad H \phi(\vec{x}) = E \phi(\vec{x})$$

$$H = \frac{p^2}{m} = -\frac{\hbar^2}{m} \nabla^2$$

For a geometry whose line element is given by

$$dl^2 = h_1^2 du_1^2 + h_2^2 du_2^2 + h_3^2 du_3^2$$

the Laplacian is defined as follows.

$$\nabla^2 := \frac{1}{\sqrt{g}} \partial_i ((g^{-1})_{ij} \sqrt{g} \partial_j)$$

where

$$g_{ij} = \begin{pmatrix} h_1^2 & & \\ & h_2^2 & \\ & & h_3^2 \end{pmatrix}$$

$$g_{ij}^{-1} = \begin{pmatrix} 1/h_1^2 & & \\ & 1/h_2^2 & \\ & & 1/h_3^2 \end{pmatrix}$$

$$g = \det g_{ij} = h_1^2 h_2^2 h_3^2$$

(16)

$$\therefore \nabla^2 = \frac{1}{h_1 h_2 h_3} \left( \frac{\partial}{\partial u_1} \left( \frac{h_1 h_2 h_3}{h_1} \frac{\partial}{\partial u_1} \right) + \frac{\partial}{\partial u_2} \left( \frac{h_1 h_2 h_3}{h_2} \frac{\partial}{\partial u_2} \right) + \frac{\partial}{\partial u_3} \left( \frac{h_1 h_2 h_3}{h_3} \frac{\partial}{\partial u_3} \right) \right)$$

In cylindrical coordinates, we have

$$dl^2 = ds^2 + s^2 d\varphi^2 + dz^2$$

$$\therefore g_{ij} = \begin{pmatrix} 1 & & \\ & s^2 & \\ & & 1 \end{pmatrix}, \quad (g^{-1})_{ij} = \begin{pmatrix} 1 & & \\ & 1/s^2 & \\ & & 1 \end{pmatrix}, \quad \text{let } g_{ij} = s^2$$

~~.....~~

$$\begin{aligned} \therefore \nabla^2 &= \frac{1}{s} \frac{\partial}{\partial s} \left( s \frac{\partial}{\partial s} \right) + \frac{1}{s} \frac{\partial}{\partial \varphi} \left( \frac{1}{s^2} s \frac{\partial}{\partial \varphi} \right) + \frac{1}{s} \frac{\partial}{\partial z} \left( s \frac{\partial}{\partial z} \right) \\ &= \frac{1}{s} \frac{\partial}{\partial s} \left( s \frac{\partial}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2}{\partial \varphi^2} + \frac{\partial^2}{\partial z^2} \end{aligned}$$


---



(17)

$$-\frac{\hbar^2}{2m} \nabla^2 \phi = E \phi$$

$$\nabla^2 \phi = -\frac{2mE}{\hbar^2} \phi =: -k^2 \phi$$

$$\phi(\vec{x}) = S(s) \Phi(\varphi) Z(z)$$

$$\nabla^2 \phi = \frac{1}{s} \frac{\partial}{\partial s} \left( s \frac{\partial \phi}{\partial s} \right) + \frac{1}{s^2} \frac{\partial^2 \phi}{\partial \varphi^2} + \frac{\partial^2 \phi}{\partial z^2}$$

$$= \Phi Z \frac{(sS')'}{s} + S Z \frac{1}{s^2} \Phi'' + S \Phi Z''$$

$$\Phi Z \frac{(sS')'}{s} + S Z \frac{1}{s^2} \Phi'' + S \Phi Z'' = -k^2 S \Phi Z \quad \Big| \frac{1}{S \Phi Z}$$

$$\frac{(sS')'}{sS} + \frac{1}{s^2} \underbrace{\frac{\Phi''}{\Phi}}_{-m^2} + \underbrace{\frac{Z''}{Z}}_{-n^2} = -k^2$$

$$\Phi(\varphi) = e^{im\varphi} ; \quad \Phi(\varphi + 2\pi) = \Phi(\varphi) \Rightarrow m \in \mathbb{Z}$$

$$Z(z) = A \sin nz + B \cos nz$$

$$Z(0) = 0 \Rightarrow B = 0$$

$$Z(L) = 0 \Rightarrow n = \frac{l\pi}{L}, \quad l \in \mathbb{Z}^+$$

$$\therefore z(z) = A \sin \frac{l\pi z}{L}$$

$$\frac{(sS')'}{sS} - \frac{m^2}{s^2} - n^2 = -k^2 \quad \Bigg| \quad s^2 S$$

$$\underbrace{s(sS')'}_{s^2 S'' + sS'} - m^2 S - n^2 s^2 S = -k^2 s^2 S$$

$$s^2 S'' + sS' + ((k^2 - n^2)s^2 - m^2) S = 0 \quad \text{Bessel eqn}$$

$$S(s) = A J_m(\sqrt{k^2 - n^2} s) + B N_m(\sqrt{k^2 - n^2} s)$$

Both Bessel I and Bessel II will be used  $\because$   
the region is away from both extremes (0 and  $\infty$ ).

$$\begin{cases} S(a) = A J_m(\sqrt{k^2 - n^2} a) + B N_m(\sqrt{k^2 - n^2} a) = 0 & (*) \\ S(b) = A J_m(\sqrt{k^2 - n^2} b) + B N_m(\sqrt{k^2 - n^2} b) = 0 & (**) \end{cases}$$

$$(*) \Rightarrow A = - \frac{B N_m(\sqrt{k^2 - n^2} a)}{J_m(\sqrt{k^2 - n^2} a)}$$

$$(**) \Rightarrow - \frac{B N_m(\sqrt{k^2 - n^2} a)}{J_m(\sqrt{k^2 - n^2} a)} + B N_m(\sqrt{k^2 - n^2} b) = 0$$

$$J_m(\sqrt{k^2 - n^2} b)$$

(19)

$$J_m(\sqrt{k^2 - n^2}a) N_m(\sqrt{k^2 - n^2}b) - J_m(\sqrt{k^2 - n^2}b) N_m(\sqrt{k^2 - n^2}a) = 0$$

Assume  $\exists \beta_{ml}$ :  $\beta_{ml}$  solve the eqn above. Then

$$\beta_{ml} = \sqrt{k^2 - n^2}, \quad j \in \mathbb{Z}^+ \quad (\exists \infty \text{ many roots of that eqn})$$

$$\therefore k^2 = \beta_{ml}^2 + n^2 = \beta_{ml}^2 + \left(\frac{l\pi}{L}\right)^2$$

$$\frac{2mE}{\hbar^2} = \beta_{ml}^2 + \left(\frac{l\pi}{L}\right)^2$$

$$E_{lmj} = \frac{\hbar^2}{2m} \left( \beta_{mj}^2 + \frac{l^2 \pi^2}{L^2} \right)$$

(20)

Sakurai 2.30Continuity eqn for  $\psi$ :

$$i\hbar \frac{\partial \psi}{\partial t} = H\psi = \frac{p^2}{2m} \psi + V\psi$$

$$= -\frac{\hbar^2}{2m} \nabla^2 \psi + V\psi, \quad \text{assume } V \text{ is real valued}$$

$$\psi^* (\text{eqn}) - (\text{eqn})^* \psi = 0$$

$$\psi^* \left( i\hbar \dot{\psi} + \frac{\hbar^2}{2m} \psi'' - V\psi \right) - \left( -i\hbar \dot{\psi}^* + \frac{\hbar^2}{2m} \psi^{*''} - V\psi^* \right) \psi = 0$$

$$i\hbar \underbrace{\left( \psi^* \dot{\psi} + \dot{\psi}^* \psi \right)}_{\frac{\partial}{\partial t} \psi^* \psi} + \frac{\hbar^2}{2m} \underbrace{\left( \psi^* \psi'' - \psi^{*''} \psi \right)}_{\begin{aligned} &= (\psi^* \psi')' - \psi^{*'} \psi' - (\psi^{*'} \psi)' + \psi^* \psi' \\ &= (\psi^* \psi' - \psi^{*'} \psi)' \end{aligned}} = 0$$

$$i\hbar \frac{\partial |\psi|^2}{\partial t} + \frac{\hbar^2}{2m} \vec{\nabla} \cdot (\psi^* \vec{\nabla} \psi - \psi \vec{\nabla} \psi^*) = 0$$

$$\frac{\partial |\psi|^2}{\partial t} + \frac{\hbar}{2im} \vec{\nabla} \cdot (\psi^* \vec{\nabla} \psi - \psi \vec{\nabla} \psi^*) = 0$$

(21)

$$\frac{\partial \rho}{\partial t} + \vec{\nabla} \cdot \vec{J} = 0$$

$$\therefore \vec{J} = \frac{\hbar}{2im} (\psi^* \vec{\nabla} \psi - \psi \vec{\nabla} \psi^*)$$

$$= \frac{\hbar}{2im} 2i \operatorname{Im} \psi^* \vec{\nabla} \psi$$

$$= \frac{\hbar}{m} \operatorname{Im} \psi^* \vec{\nabla} \psi \quad \textcircled{=}$$

$$z = a + ib \Rightarrow b = \operatorname{Im} z = \operatorname{Re} \frac{z}{i}$$

$$\textcircled{=} \frac{\hbar}{m} \operatorname{Re} \frac{\psi^* \vec{\nabla} \psi}{i}$$

$$= \operatorname{Re} \psi^* \frac{\hbar \vec{\nabla}}{im} \psi$$

$$= \operatorname{Re} \psi^* \frac{\vec{p}}{m} \psi$$

$$\boxed{\vec{J} = \operatorname{Re} \psi^* \vec{V} \psi}$$

makes sense  $\because$  this is nonrelat. phys.

H-atom:

$$\psi(\vec{r}) \sim \underbrace{\text{Laguerre polynomials}}_{\text{real}} \times \underbrace{\text{spherical harmonics}}_{\text{complex}}$$

(22)

$$\psi^* \nabla_r \psi = \underbrace{\psi^*}_{RC^*} \frac{\hbar}{im} \underbrace{\left( \frac{\partial}{\partial r} \right)}_{RC} \underbrace{\psi}_{RC} \quad \ominus$$

$$\nabla = \hat{r} \frac{\partial}{\partial r} + \frac{\hat{\theta}}{r} \frac{\partial}{\partial \theta} + \frac{\hat{\phi}}{r \sin \theta} \frac{\partial}{\partial \phi}$$

$R$ : real part, depending only on  $r$

$C$ : complex part, depending only on angles

$$\ominus \quad RC^* \frac{\hbar}{im} C \frac{1}{r^2} \frac{\partial}{\partial r} \left( r^2 \frac{\partial}{\partial r} \right) R$$

$\underbrace{\hspace{1.5cm}}_{|C|^2}$

$$= \frac{1}{i} (\text{real})$$

$\therefore J_r = 0 \quad \therefore$  no radial flow

$$\psi^* \nabla_{\theta} \psi = \psi^* \frac{\hbar}{im} \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} \psi$$

$$= R^* C^* \frac{\hbar}{im} \frac{1}{r \sin \theta} \frac{\partial}{\partial \theta} R C$$

Angular part contains complex unit only via  $e^{im\phi}$  so, this bit also gives 0.

(23)

$$\begin{aligned}\psi^* V_\phi \psi &= \psi^* \frac{\hbar}{i\mu} \frac{1}{r \sin \theta} \frac{\partial}{\partial \phi} \psi \\ &\quad \downarrow \text{real } \times e^{im\phi} \\ &= R e^{-im\phi} \frac{\hbar}{i\mu r \sin \theta} \frac{\partial}{\partial \phi} R e^{im\phi} \\ &= \underbrace{(R e^{-im\phi})(R e^{im\phi})}_{|\psi|^2} i m \frac{\hbar}{\mu r \sin \theta} \\ &= \frac{i \hbar m |\psi|^2}{\mu r \sin \theta}\end{aligned}$$

$$\therefore \vec{J} = J_\phi \hat{\phi}$$

$$\boxed{\vec{J} = \frac{i \hbar m |\psi|^2}{\mu r \sin \theta} \hat{\phi}}$$

Quote of the week:

"If you haven't found something strange during the day, it hasn't been much of a day."

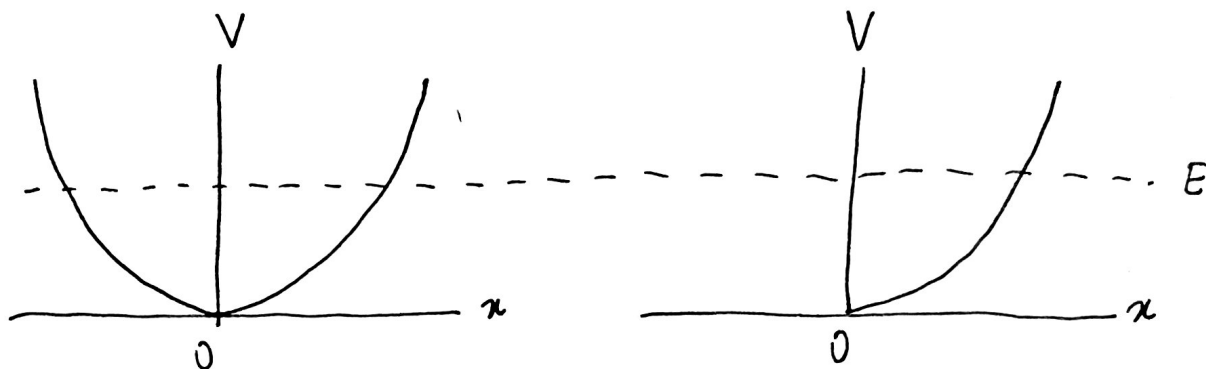
- Wheeler

①

# 507 RECIT 4

## Sakurai 2.22

$$V(x) = \begin{cases} \frac{1}{2} kx^2, & x > 0 \\ \infty, & x < 0 \end{cases} \quad \text{"half oscillator"}$$



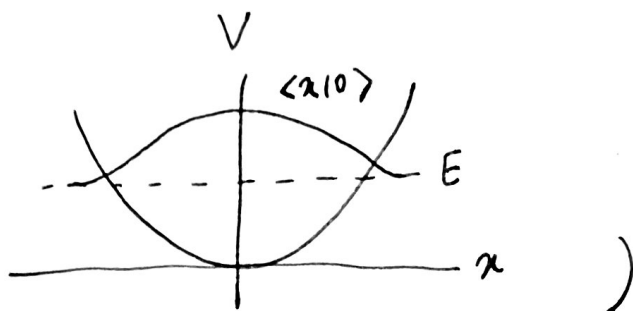
Since we will be solving the same Schrodinger equation in the region  $x > 0$ , we should have the same solutions. The major difference will be in the boundary conditions. For "half oscillator", we have to ~~impose~~ impose

$$\langle x | n \rangle \Big|_{x=0} = \langle 0 | n \rangle = 0 \quad \forall n$$

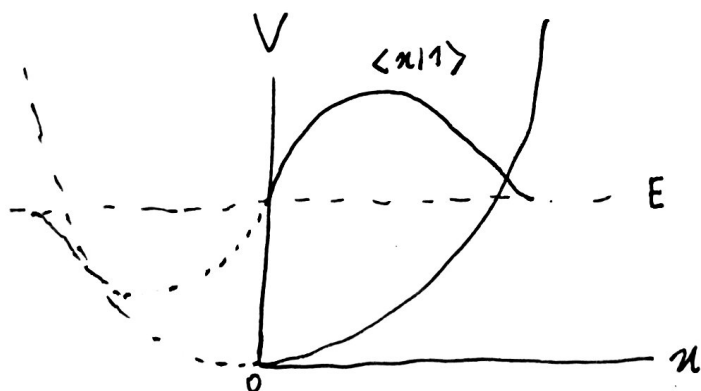
Since the full oscillator has even (symmetric) pot, the eigenfunctions of the Hamiltonian should be either even or odd about the origin ( $\because$  parity is conserved). Since the ground state of the full oscillator is even, (see



(2)



by induction all the solutions w/  $n$  even should behave like this.  $\therefore$  the half oscillator has the odd solutions of the full oscillator to satisfy the BCs:



therefore the ground state of the half oscillator is  $|1\rangle$ . Since our domain has also change, we need to redefine  $\langle x|0\rangle$  from scratch:

$$a_{\pm} := \sqrt{\frac{1}{2m\omega\hbar}} (m\omega\hbar \hat{x} \mp i\hat{p})$$

$$a_-|0\rangle = 0$$

$$\langle x|a_-|0\rangle = \langle x| \frac{m\omega\hbar \hat{x} - i\hat{p}}{\sqrt{2m\omega\hbar}} |0\rangle$$

$$= \frac{1}{\sqrt{2m\omega\hbar}} (m\omega\hbar \langle x|\hat{x}|0\rangle - i\langle x|\hat{p}|0\rangle)$$

③

$$= \frac{1}{\sqrt{2m\omega\hbar}} \left( m\omega x \langle x|0 \rangle + i \frac{\hbar}{i} \frac{\partial}{\partial x} \langle x|0 \rangle \right)$$

$$= 0$$

$$m\omega x \langle x|0 \rangle + \hbar \frac{\partial}{\partial x} \langle x|0 \rangle = 0$$

$$\frac{\partial \langle x|0 \rangle}{\langle x|0 \rangle} = - \frac{m\omega}{\hbar} x \partial x =: - \frac{x \partial x}{x_0^2}, \quad x_0^2 := \frac{\hbar}{m\omega}$$

$$\therefore \langle x|0 \rangle = N e^{-x^2/2x_0^2}$$

~~XXXXXXXXXX~~

$$\bullet a_+ |0\rangle = |1\rangle$$

$$\therefore \langle x|1\rangle = \langle x|a_+|0\rangle$$

$$= \langle x| \frac{m\omega X - iP}{\sqrt{2m\omega\hbar}} |0\rangle$$

$$= \frac{1}{\sqrt{2m\omega\hbar}} \left( m\omega \langle x|X|0\rangle - i \langle x|P|0\rangle \right)$$

$$= \frac{1}{\sqrt{2m\omega\hbar}} \left( m\omega x \langle x|0 \rangle - i \frac{\hbar}{i} \frac{\partial}{\partial x} \langle x|0 \rangle \right)$$

$$= \frac{1}{\sqrt{2m\omega\hbar}} \left( m\omega x \langle x|0 \rangle - \hbar \frac{\partial}{\partial x} \langle x|0 \rangle \right)$$

$$= \frac{1}{\sqrt{2m\omega\hbar}} \hbar \left( \frac{m\omega}{\hbar} x \langle x|0 \rangle - \frac{\partial}{\partial x} \langle x|0 \rangle \right)$$

(4)

$$= \sqrt{\frac{\hbar}{2m\omega}} \left( \frac{m\omega}{\hbar} x \langle x|0 \rangle - \frac{\partial}{\partial x} \langle x|0 \rangle \right)$$

$$= \sqrt{\frac{x_0^2}{2}} \left( \frac{x}{x_0^2} \langle x|0 \rangle - \frac{\partial}{\partial x} \langle x|0 \rangle \right)$$

$$\frac{\partial}{\partial x} \langle x|0 \rangle = \frac{\partial}{\partial x} N e^{-x^2/2x_0^2}$$

$$= -N \frac{x}{x_0^2} e^{-x^2/2x_0^2} = -\frac{x}{x_0^2} \langle x|0 \rangle$$

$$\therefore \langle x|1 \rangle = \sqrt{\frac{x_0^2}{2}} \left( \frac{x}{x_0^2} \langle x|0 \rangle + \frac{x}{x_0^2} \langle x|0 \rangle \right)$$

$$= \sqrt{\frac{x_0^2}{2}} \frac{2x}{x_0^2} \langle x|0 \rangle$$

$$= \frac{\sqrt{2} x}{x_0} N e^{-x^2/2x_0^2}$$

$$\langle 1|1 \rangle = 1$$

$$= \int_0^\infty dx \langle 1|x \rangle \langle x|1 \rangle$$

$$= \int_0^\infty dx \frac{2N^2}{x_0^2} x^2 e^{-x^2/x_0^2}$$

$$= \frac{2N^2}{x_0^2} \int_0^\infty dx x^2 e^{-x^2/x_0^2}$$

⑤

$$\int_0^{\infty} dr r^2 e^{-\alpha r^2} = ?$$

$$\begin{aligned} \int d^3r e^{-\alpha \vec{r}^2} &= \int_{-\infty}^{\infty} dx \int_{-\infty}^{\infty} dy \int_{-\infty}^{\infty} dz e^{-\alpha(x^2+y^2+z^2)} \\ &= \left( \int_{-\infty}^{\infty} dx e^{-\alpha x^2} \right)^3 = \left( \sqrt{\frac{\pi}{\alpha}} \right)^3 \end{aligned}$$

$$\int d^3r e^{-\alpha \vec{r}^2} = 4\pi \int_0^{\infty} dr r^2 e^{-\alpha r^2}$$

$$\therefore \int_0^{\infty} dr r^2 e^{-\alpha r^2} = \frac{1}{4\pi} \left( \sqrt{\frac{\pi}{\alpha}} \right)^3$$

$$\therefore \int_0^{\infty} dx x^2 e^{-x^2/\alpha_0^2} = \frac{1}{4\pi} (\alpha_0^2 \pi)^{3/2}$$

$$\therefore \langle 1|1 \rangle = \frac{2N^2}{\alpha_0^2} \frac{1}{4\pi} (\alpha_0^2 \pi)^{3/2}$$

$$\therefore N^2 = \frac{2 \cdot 4\pi \alpha_0^2}{4 (\alpha_0^2 \pi)^{3/2}}$$

~~Ground state of half oscillator~~

$$\therefore \langle x|1 \rangle = \sqrt{\frac{2\pi\alpha_0^2}{(\alpha_0^2\pi)^{3/2}}} \frac{\sqrt{2}\alpha_0}{\alpha_0} e^{-x^2/2\alpha_0^2} \quad 0 < x < \infty$$

$$E_1 = \hbar\omega \left( n + \frac{1}{2} \right) \Big|_{n=1} = \frac{3}{2} \hbar\omega \quad \text{energy of ground state}$$

(6)

$$\langle X^2 \rangle = \langle 1 | X^2 | 1 \rangle$$

$$= \int_0^\infty dx \langle 1 | x \rangle x^2 \langle x | 1 \rangle$$

$$= \frac{2\pi\kappa_0^2}{(\kappa_0^2\pi)^{3/2}} \frac{2}{\kappa_0^2} \int_0^\infty dx x^4 e^{-x^2/\kappa_0^2}$$

$$\int_0^\infty dx x^2 e^{-\alpha x^2} = \frac{1}{4\pi} \left( \sqrt{\frac{\pi}{\alpha}} \right)^3 = \frac{\pi^{3/2}}{4\pi} \alpha^{-3/2} \quad \left| -\frac{\partial}{\partial \alpha} \right.$$

$$\int_0^\infty dx x^4 e^{-\alpha x^2} = \frac{\pi^{3/2}}{4\pi} \frac{3}{2} \alpha^{-5/2} = \frac{3\pi^{3/2}}{8\pi} \alpha^{-5/2}$$

$$\therefore \int_0^\infty dx x^4 e^{-x^2/\kappa_0^2} = \frac{3\pi^{3/2}}{8\pi} (\kappa_0^2)^{5/2} = \frac{3\pi^{3/2} \kappa_0^5}{8\pi}$$

$$\therefore \langle X^2 \rangle = \frac{2\pi\kappa_0^2}{(\kappa_0^2\pi)^{3/2}} \frac{2}{\kappa_0^2} \frac{3\pi^{3/2} \kappa_0^5}{8\pi}$$

$$\boxed{\langle X^2 \rangle = \frac{3\pi\kappa_0^2}{2}}$$

⑦

### Solution 2.27

"Density of states" is defined as the Jacobian of the transformation from phase space to the "energy space".

$$\frac{d^3x d^3p}{h^3} = D(E) dE$$

For a free particle,  $\nexists$  any dependence on  $x$ , so  $d^3x$  can be directly integrated to give  $V$ , volume.

$$\frac{V}{h^3} d^3p = D(E) dE$$

For a free particle,  $E = \vec{p}^2/2m$ , so there is no angular dependence, either:

$$d^3p = |\vec{p}|^2 d|\vec{p}| d\Omega = 4\pi |\vec{p}|^2 d|\vec{p}|$$

$$\therefore \frac{V}{h^3} 4\pi |\vec{p}|^2 d|\vec{p}| = D(E) dE$$

$$\begin{aligned} \therefore D(E) &= \frac{V}{h^3} 4\pi \underbrace{|\vec{p}|^2}_{2mE} \underbrace{\left| \frac{d|\vec{p}|}{dE} \right|}_{\left| \frac{d}{dE} (2mE)^{1/2} \right|} \\ &= \frac{V}{h^3} 4\pi 2mE \cancel{\frac{1}{2}} (2mE)^{-1/2} \cancel{2m} \end{aligned}$$

⑧

$$= \frac{V}{h^3} 8\pi m^2 E (2mE)^{-1/2}$$

$$\boxed{D(E) = \frac{V}{h^3} \frac{8\pi m^2}{\sqrt{2m}} \sqrt{E}} \quad 3D$$

From this, you can switch to density of states in terms of  $k$  or  $p$  or whatever parameter you want to control: (As long as you know its dependence on  $E$ )

$$D(E) dE = D(\lambda) d\lambda \quad (\lambda: \text{not wavelength but arbitrary parameter})$$

$$D(\lambda) = D(E(\lambda)) \left| \frac{dE}{d\lambda} \right|$$

Why the absolute value?  $\therefore$  the Jacobian is an intrinsically positive quantity.

In 2D:

$$\frac{d^2x d^2p}{h^2} = D(E) dE$$

$$\frac{A}{h^2} \underbrace{|\vec{p}| d|\vec{p}|}_{\sqrt{2mE}} d\varphi = D(E) dE$$

$$D(E) = \frac{A}{h^2} \sqrt{2mE} \underbrace{\left| \frac{d|\vec{p}|}{dE} \right|}_{\frac{m}{\sqrt{2mE}}} d\varphi = \frac{A}{h^2} \sqrt{2mE} \frac{m}{\sqrt{2mE}} d\varphi$$

indep of  $E$

⑨

in 1D:

$$\frac{dx dp}{h} = D(E) dE$$

$$\frac{L}{h} dp = D(E) dE$$

$$D(E) = \frac{L}{h} \left| \frac{dp}{dE} \right| = \frac{L}{h} \frac{m}{\sqrt{2mE}}$$

$$D_{3D}(E) \propto \cancel{\sqrt{E}} E^{1/2}$$

$$D_{2D}(E) \propto E^0$$

$$D_{1D}(E) \propto E^{-1/2}$$



(10)

Salmuri 2.32

$$K(\vec{x}', t'; \vec{x}, t) = \langle \vec{x}' | e^{-\frac{i}{\hbar} H(t' - t)} | \vec{x} \rangle$$

$$Z := \int d^3x \langle \vec{x} | e^{-\frac{i}{\hbar} Ht} | \vec{x} \rangle \Big|_{\frac{it}{\hbar} \rightarrow \beta}$$

$$= \int d^3x \langle \vec{x} | e^{-\beta H} | \vec{x} \rangle$$

$$= \int d^3x \langle \vec{x} | e^{-\beta H} \sum_n |n\rangle \langle n| \vec{x} \rangle$$

$$= \sum_n e^{-\beta E_n} \underbrace{\int d^3x \langle \vec{x} | n \rangle \langle n | \vec{x} \rangle}_1$$

1 if the eigenkets are normalized.

(or at least some const,  $N^2$ )

$$= \sum_n e^{-\beta E_n}$$

As  $\beta \rightarrow \infty$ , less and less terms contribute to the sum, so we get

$$Z = e^{-\beta E_0}$$

where  $E_0$  is the ground-state energy.

(11) one way to isolate (or extract)  $E_0$  is to take derivatives:

$$\frac{\partial Z}{\partial \beta} = -E_0 e^{-\beta E_0} = -Z E_0$$

$$\therefore \boxed{E_0 = -\frac{1}{Z} \frac{\partial Z}{\partial \beta}} \quad \text{in the limit } \beta \rightarrow \infty$$

Particle in a box: For a box of size  $[0, L]$ ,

$$E_n = \frac{\hbar^2 \pi^2 n^2}{2mL^2}, \quad n \in \mathbb{Z}^+$$

$$=: \varepsilon n^2$$

$$Z = \sum_{n \geq 1} e^{-\beta E_n} = \sum_{n \geq 1} e^{-n^2 \beta \varepsilon}$$

For  $\beta \rightarrow \infty$ ,

$$Z = e^{-\beta \varepsilon} + e^{-4\beta \varepsilon} + \dots = e^{-\beta \varepsilon} + O(e^{-4\beta \varepsilon}) \approx e^{-\beta \varepsilon}$$

$$\frac{\partial Z}{\partial \beta} = -\varepsilon e^{-\beta \varepsilon} \Rightarrow E_1 = -\frac{1}{Z} \frac{\partial Z}{\partial \beta} = \varepsilon \quad \checkmark$$

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Quote of the week:

"I think I can safely say that nobody understands quantum mechanics."

- Feynman

①

EXTRA 1

$$\begin{aligned}
\langle p | X | \alpha \rangle &= \int dx \langle p | X | x \rangle \langle x | \alpha \rangle \\
&= \int dx dp' \langle p | x \rangle x \langle x | p' \rangle \langle p' | \alpha \rangle \\
&= \int dx dp' \frac{e^{-ipx/\hbar}}{\sqrt{2\pi\hbar}} \frac{e^{ip'x/\hbar}}{\sqrt{2\pi\hbar}} x \langle p' | \alpha \rangle \\
&= \int dp' \left( \int \frac{dx}{2\pi\hbar} x e^{i(p'-p)x/\hbar} \right) \langle p' | \alpha \rangle \\
&= \int dp' \left( -\frac{\hbar}{i} \frac{\partial}{\partial p} \int \frac{dx}{2\pi\hbar} e^{i(p'-p)x/\hbar} \right) \langle p' | \alpha \rangle \\
&= -\frac{\hbar}{i} \frac{\partial}{\partial p} \int dp' \delta(p'-p) \langle p' | \alpha \rangle
\end{aligned}$$

$$\boxed{\langle p | X | \alpha \rangle = -\frac{\hbar}{i} \frac{\partial}{\partial p} \langle p | \alpha \rangle}$$

$$i\hbar \frac{\partial}{\partial t} |\alpha(t)\rangle = H |\alpha(t)\rangle$$

$$H = \frac{p^2}{2m} + V(x), \quad V(x) = -qEx$$

$$\therefore \frac{\partial H}{\partial t} = 0$$

$$\therefore H|\alpha\rangle = E|\alpha\rangle$$

$$\langle p | H | \alpha \rangle = E \langle p | \alpha \rangle$$

(2)

$$\langle p | \frac{p^2}{2m} - qE\lambda | \alpha \rangle = E \langle p | \alpha \rangle$$

$$\frac{p^2}{2m} \langle p | \alpha \rangle - qE \frac{-\hbar}{i} \frac{\partial}{\partial p} \langle p | \alpha \rangle = E \langle p | \alpha \rangle$$

$$\langle p | \alpha \rangle' \frac{qE\hbar}{i} + \langle p | \alpha \rangle \frac{p^2}{2m} = E \langle p | \alpha \rangle \quad \Big| \frac{i}{qE\hbar}$$

$$\langle p | \alpha \rangle' + \frac{ip^2}{2mqE\hbar} \langle p | \alpha \rangle = \frac{iE}{qE\hbar} \langle p | \alpha \rangle$$

Canonical form:

$$y' + (Ax^2 + B)y = 0$$

$$\frac{dy}{y} = -(Ax^2 + B) dx$$

$$\ln y = -\left(\frac{Ax^3}{3} + Bx\right) + \ln y(0)$$

$$y(x) = y(0) e^{-(Ax^3/3 + Bx)}$$

Put  $x \rightarrow p$

$$y \rightarrow \langle p | \alpha \rangle$$

$$A \rightarrow \frac{i}{2mqE\hbar}$$

$$B \rightarrow \frac{iE}{qE\hbar}$$

Normalization (or initial condition) is open to discussion.

3

EXTRA 2

2.16

(see Perit.3 notes.)

2.17

$$(a) \quad \hat{x} = \sqrt{\frac{\hbar}{2m\omega}} (a_+ + a_-)$$

$$|\alpha\rangle = a|0\rangle + b|1\rangle, \quad |a|^2 + |b|^2 = 1$$

$$\begin{aligned} \langle \hat{x} \rangle &= (a^* \langle 0| + b^* \langle 1|) \sqrt{\frac{\hbar}{2m\omega}} (a_+ + a_-) (a|0\rangle + b|1\rangle) \\ &= \sqrt{\frac{\hbar}{2m\omega}} (a^* \langle 0| + b^* \langle 1|) (a|1\rangle + \sqrt{2} b|2\rangle + b|0\rangle) \\ &= \sqrt{\frac{\hbar}{2m\omega}} (a^* b + b^* a) \end{aligned}$$

Maximize  $a^* b + b^* a$  subject to the constraint  $|a|^2 + |b|^2 - 1 = 0$ :

$$f := a^* b + b^* a + \lambda (a^* a + b^* b - 1) \rightarrow \text{the trick is, treat } a \text{ and } a^* \text{ (and } b \text{ and } b^*) \text{ as indep. parameters.}$$

$$\frac{\partial f}{\partial a} = b^* + \lambda a^* = 0$$

$$\frac{\partial f}{\partial a^*} = b + \lambda a = 0$$

$$\frac{\partial f}{\partial b} = a^* + \lambda b^* = 0$$

$$\frac{\partial f}{\partial b^*} = a + \lambda b = 0$$

(4)

$$\left. \begin{aligned} a^* &= -\frac{1}{\lambda} b^* \\ a^* &= -\lambda b^* \end{aligned} \right\} -\frac{1}{\lambda} = -\lambda \quad \therefore \lambda = \pm 1$$

$$\left. \begin{aligned} a &= -\frac{1}{\lambda} b \\ a &= -\lambda b \end{aligned} \right\} \text{ same}$$

$$a^* a + b^* b = 1$$

$$(-\lambda b^*)(-\lambda b) + b^* b = 1$$

$$\underbrace{\lambda^2}_{1} b^* b + b^* b = 1$$

$$2b^* b = 1$$

$$\therefore |b| = \frac{1}{\sqrt{2}}$$

$$\therefore |a| = \frac{1}{\sqrt{2}}$$

Assume  $a, b \in \mathbb{R}^+$  :

$$\boxed{|\alpha\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}}$$

("Construct a linear combination...")

5)

$$(b) \quad |\alpha(0)\rangle = \frac{|0\rangle + |1\rangle}{\sqrt{2}}$$

$$|\alpha(t)\rangle = e^{-iHt/\hbar} |\alpha(0)\rangle$$

$$|\alpha(t)\rangle = \frac{e^{-iE_0 t/\hbar} |0\rangle + e^{-iE_1 t/\hbar} |1\rangle}{\sqrt{2}}, \quad t > 0, \quad E_n = \hbar\omega\left(n + \frac{1}{2}\right)$$

In Schr. pic:

$$\langle X \rangle = \langle \alpha(t) | X | \alpha(t) \rangle$$

$$= \frac{e^{iE_0 t/\hbar} \langle 0| + e^{iE_1 t/\hbar} \langle 1|}{\sqrt{2}} \sqrt{\frac{\hbar}{2m\omega}} (a_+ + a_-)$$

$$\times \frac{e^{-iE_0 t/\hbar} |0\rangle + e^{-iE_1 t/\hbar} |1\rangle}{\sqrt{2}}$$

$$= \frac{1}{2} \sqrt{\frac{\hbar}{2m\omega}} (e^{iE_0 t/\hbar} \langle 0| + e^{iE_1 t/\hbar} \langle 1|)$$

$$\times (e^{-iE_0 t/\hbar} |1\rangle + e^{-iE_1 t/\hbar} |0\rangle + ( ) |2\rangle)$$

$$= \frac{1}{2} \sqrt{\frac{\hbar}{2m\omega}} (e^{i(E_0 - E_1)t/\hbar} + e^{-i(E_0 - E_1)t/\hbar})$$

$$\langle X \rangle = \sqrt{\frac{\hbar}{2m\omega}} \cos \frac{(E_0 - E_1)t}{\hbar}$$

⑥

In Heisenberg ~~pic~~ pic:

$$|\alpha(t)\rangle = |\alpha(0)\rangle$$

$$X(t) = U^\dagger(t) X U(t)$$

$$= e^{iHt/\hbar} X e^{-iHt/\hbar}$$

→ compute it either from Heis. eqn of motion or from Baker-Hausdorff formula

$$H = \frac{P^2}{2m} + \frac{1}{2} m \omega^2 X^2$$

$$[X, H] = \frac{1}{2m} [X, P^2] = \frac{i\hbar P}{m}$$

$$\therefore \dot{X} = \frac{1}{m} P$$

$$[P, H] = \frac{1}{2} m \omega^2 [P, X^2] = \frac{m \omega^2}{2} (-2i\hbar X)$$

$$= -i\hbar m \omega^2 X$$

$$\therefore \dot{P} = -m \omega^2 X$$

$$\therefore \ddot{X} = -\omega^2 X \quad \text{et} \quad \ddot{P} = -\omega^2 P$$

$$X(t) = A \cos \omega t + B \sin \omega t$$

$$P(t) = C \cos \omega t + D \sin \omega t$$

$$\dot{X} = -\omega A \sin \omega t + \omega B \cos \omega t$$

$$\dot{P} = -\omega C \sin \omega t + \omega D \cos \omega t$$



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$$-\omega A \sin \omega t + \omega B \cos \omega t = \frac{1}{m} C \cos \omega t + \frac{1}{m} D \sin \omega t$$

Since  $\sin$  and  $\cos$  are linearly indep.,

$$-\omega A = \frac{1}{m} D$$

$$\omega B = \frac{1}{m} C$$

Meantime,

$$A = X(0), \quad C = P(0)$$

$$\therefore D = -m\omega X(0) \quad \text{et} \quad B = \frac{1}{m\omega} P(0)$$

$$\therefore X(t) = X \cos \omega t + \frac{1}{m\omega} P \sin \omega t$$

$$= \sqrt{\frac{\hbar}{2m\omega}} (a^+ + a) \overset{\cos \omega t}{1} + \frac{1}{m\omega} i \sqrt{\frac{\hbar m\omega}{2}} (a^+ - a) \sin \omega t$$

$$= \sqrt{\frac{\hbar}{2m\omega}} \left( a_+ (\cos \omega t + i \sin \omega t) + a_- (\cos \omega t - i \sin \omega t) \right)$$

$$= \sqrt{\frac{\hbar}{2m\omega}} \left( e^{i\omega t} a_+ + e^{-i\omega t} a_- \right)$$

$$\therefore \langle X \rangle = \langle \alpha(0) | X(t) | \alpha(0) \rangle$$

$$= \frac{\langle 0 | + \langle 1 |}{\sqrt{2}} \sqrt{\frac{\hbar}{2m\omega}} (e^{i\omega t} a_+ + e^{-i\omega t} a_-) \frac{|0\rangle + |1\rangle}{\sqrt{2}}$$

$$= \frac{1}{2} \sqrt{\frac{\hbar}{2m\omega}} (\langle 0 | + \langle 1 |) (e^{i\omega t} |1\rangle + (1/2) + e^{-i\omega t} |0\rangle)$$

$$= \frac{1}{2} \sqrt{\frac{\hbar}{2m\omega}} \underbrace{(e^{-i\omega t} + e^{i\omega t})}_{2 \cos \omega t}$$

8

$$= \frac{1}{2} \sqrt{\frac{\hbar}{2m\omega}} \cos \omega t \quad \text{same result.}$$

(c) Assume schr. pic:

$$X^2 = \frac{\hbar}{2m\omega} (a_+ + a_-)^2, \quad [a_{\pm}, a_{\mp}] = \mp 1$$

$$= \frac{\hbar}{2m\omega} (a_+^2 + a_-^2 + \underbrace{a_+ a_-}_N + \underbrace{a_- a_+}_{a_+ a_- + [a_-, a_+]})$$

$$= \frac{\hbar}{2m\omega} (a_+^2 + a_-^2 + 2N + 1)$$

$$\langle X^2 \rangle = \frac{e^{iE_0 t/\hbar} \langle 0| + e^{-iE_1 t/\hbar} \langle 1|}{\sqrt{2}} \frac{\hbar}{2m\omega} \times (a_+^2 + a_-^2 + 2N + 1) \frac{e^{-iE_0 t/\hbar} |0\rangle + e^{-iE_1 t/\hbar} |1\rangle}{\sqrt{2}} \quad (\odot)$$

$$a_+^2 |0\rangle = \sqrt{2} |2\rangle$$

$$a_-^2 |0\rangle = 0$$

$$a_+^2 |1\rangle = \sqrt{2 \times 3} |3\rangle = \sqrt{6} |3\rangle$$

$$a_-^2 |1\rangle = 0$$

$$\odot \frac{\hbar}{2m\omega} \frac{1}{2} (e^{iE_0 t/\hbar} \langle 0| + e^{iE_1 t/\hbar} \langle 1|)$$

$$\times (e^{-iE_0 t/\hbar} \sqrt{2} |2\rangle + e^{-iE_0 t/\hbar} |0\rangle + e^{-iE_1 t/\hbar} \sqrt{6} |3\rangle + 3e^{-iE_1 t/\hbar} |1\rangle)$$

$$= \frac{\hbar}{2m\omega} \frac{1}{2} (1+3) = \frac{\hbar}{2m\omega} 2$$

⑨

$$\therefore \langle \Delta X^2 \rangle = \langle X^2 \rangle - \langle X \rangle^2$$

$$\langle \Delta X^2 \rangle = \frac{\hbar}{2m\omega} \left( 2 - \cos^2 \frac{\Delta_{01} t}{\hbar} \right)$$

$$\Delta_{01} := E_0 - E_1$$

2.20

$$\begin{cases} J_{\pm} := a_{\pm}^{\dagger} a_{\mp} \hbar \\ J_z := \frac{\hbar}{2} (a_+^{\dagger} a_+ - a_-^{\dagger} a_-) \\ N := a_+^{\dagger} a_+ + a_-^{\dagger} a_- \end{cases}$$

Known:  $[a_{\pm}^{\dagger}, a_{\pm}] = -1$ ,  $[a_{\pm}, a_{\pm}^{\dagger}] = +1$

$[a_{\pm}, a_{\mp}] = 0 \because$  assumed indep. (also for combos that contain  $^{\dagger}$ )

Let

$$N_{\pm} := a_{\pm}^{\dagger} a_{\pm}$$

$$\begin{aligned} [J_z, J_+] &= \left[ \frac{\hbar}{2} (a_+^{\dagger} a_+ - a_-^{\dagger} a_-), \hbar a_+^{\dagger} a_- \right] \\ &= \frac{\hbar^2}{2} \left( [a_+^{\dagger} a_+, a_+^{\dagger} a_-] - [a_-^{\dagger} a_-, a_+^{\dagger} a_-] \right) \\ &= \frac{\hbar^2}{2} \left( \underbrace{[a_+^{\dagger} a_+, a_+^{\dagger}]}_{\substack{a_+^{\dagger} [a_+, a_+^{\dagger}] \\ +1}} a_- - a_+^{\dagger} \underbrace{[a_-^{\dagger} a_-, a_-]}_{\substack{[a_-^{\dagger}, a_-] a_- \\ -1}} \right) \end{aligned}$$

(10)

$$= \frac{\hbar^2}{2} (a_+^\dagger a_- + a_+^\dagger a_-)$$

$$= \hbar^2 a_+^\dagger a_-$$

$$\therefore \boxed{[J_z, J_+] = \hbar J_+}$$

$$[J_z, J_-] = \left[ \frac{\hbar}{2} (a_+^\dagger a_+ - a_-^\dagger a_-), \hbar a_-^\dagger a_+ \right]$$

$$= \frac{\hbar^2}{2} ([a_+^\dagger a_+, a_-^\dagger a_+] - [a_-^\dagger a_-, a_-^\dagger a_+])$$

$$= \frac{\hbar^2}{2} (a_-^\dagger \underbrace{[a_+^\dagger a_+, a_+]}_{\substack{[a_+^\dagger, a_+] a_+ \\ -1}} - \underbrace{[a_-^\dagger a_-, a_-^\dagger]}_{+1} a_+)$$

$$= \frac{\hbar^2}{2} (-a_-^\dagger a_+ - a_-^\dagger a_+)$$

$$= -\hbar^2 a_-^\dagger a_+$$

$$\therefore \boxed{[J_z, J_-] = -\hbar J_-}$$

$$J^2 = J_x^2 + J_y^2 + J_z^2$$

$$J_\pm := J_x \pm i J_y$$

$$\left. \begin{array}{l} J_+ = J_x + i J_y \\ J_- = J_x - i J_y \end{array} \right\} J_x = \frac{J_+ + J_-}{\sqrt{2}}, \quad J_y = \frac{J_+ - J_-}{2i}$$

(11)

$$J_x^2 = \frac{J_+^2 + J_-^2 + J_+ J_- + J_- J_+}{4}$$

$$J_y^2 = \frac{-J_+^2 - J_-^2 + J_+ J_- + J_- J_+}{4}$$

$$J_x^2 + J_y^2 = \frac{1}{2} (J_+ J_- + J_- J_+)$$

$$J^2 = \frac{1}{2} (J_+ J_- + J_- J_+) + J_z^2$$

$$\begin{aligned} [J^2, J_z] &= \left[ \frac{1}{2} (J_+ J_- + J_- J_+) + J_z^2, J_z \right] \\ &= \frac{1}{2} \left( [J_+ J_-, J_z] + [J_- J_+, J_z] \right) \\ &= \frac{1}{2} \left( J_+ [J_-, J_z] + [J_+, J_z] J_- \right. \\ &\quad \left. + J_- [J_+, J_z] + [J_-, J_z] J_+ \right) \\ &= \frac{1}{2} \left( J_+ (-)(-\hbar J_-) + (-)(\hbar J_+) J_- \right. \\ &\quad \left. + J_- (-)(\hbar J_+) + (-)(-\hbar J_-) J_+ \right) \\ &= \frac{\hbar}{2} (J_+ J_- - J_+ J_- - J_- J_+ + J_- J_+) \end{aligned}$$

$$\therefore \boxed{[J^2, J_z] = 0}$$

$$J^2 = J_x^2 + J_y^2 + J_z^2$$

$$= \frac{1}{2} (J_+ J_- + J_- J_+) + J_z^2$$

(12)

~~scribbles~~

$$\begin{aligned}
&= \frac{1}{2} (\hbar a_+^\dagger a_- \hbar a_-^\dagger a_+ + \hbar a_-^\dagger a_+ \hbar a_+^\dagger a_-) + \frac{\hbar^2}{4} (a_+^\dagger a_+ - a_-^\dagger a_-)^2 \\
&= \frac{\hbar^2}{2} (a_-^\dagger a_+ a_+^\dagger + a_+ a_-^\dagger a_- a_+^\dagger) \\
&\quad + \frac{\hbar^2}{4} (a_+^\dagger a_+ a_+^\dagger a_+ + a_-^\dagger a_- a_-^\dagger a_- - a_+^\dagger a_+ a_-^\dagger a_- - a_-^\dagger a_- a_+^\dagger a_+) \quad \textcircled{=}
\end{aligned}$$

$$[a, a^\dagger] = 1 \Rightarrow aa^\dagger = 1 + N$$

$$\textcircled{=} \frac{\hbar^2}{2} (N_+ (1 + N_-) + N_- (1 + N_+))$$

$$+ \frac{\hbar^2}{4} (N_+^2 + N_-^2 - 2N_+ N_-)$$

$$\begin{aligned}
&= \frac{\hbar^2}{2} (N_+ + N_+ N_- + N_- + \cancel{N_- N_+}) \\
&\quad + \frac{1}{2} N_+^2 + \frac{1}{2} N_-^2 - \cancel{N_+ N_-}
\end{aligned}$$

$$= \frac{\hbar^2}{2} (N + \frac{1}{2} (N_+ + N_-)^2)$$

$$= \frac{\hbar^2}{2} (N + \frac{1}{2} N^2)$$

$$\therefore J^2 = \frac{\hbar^2}{2} N \left( \frac{N}{2} + 1 \right)$$

(13)

2.39

$$(a) \quad \Pi_x := p_x - \frac{eA_x}{c}$$

$$\Pi_y := p_y - \frac{eA_y}{c}$$

$$[\Pi_x, \Pi_y] = \left[ p_x - \frac{e}{c} A_x, p_y - \frac{e}{c} A_y \right]$$

$$= -\frac{e}{c} \left( [p_x, A_y] + [A_x, p_y] \right)$$

$$= -\frac{e}{c} \left( [p_x, A_y] - [p_y, A_x] \right) \quad \textcircled{=}$$

$$[p_i, f(\vec{x})] = p_i f(\vec{x}) - f(\vec{x}) p_i$$

$$= \frac{\hbar}{i} \frac{\partial}{\partial x_i} f(\vec{x}) - f(\vec{x}) \frac{\hbar}{i} \frac{\partial}{\partial x_i}$$

$$= \frac{\hbar}{i} \frac{\partial f}{\partial x_i} + f(\vec{x}) \frac{\hbar}{i} \frac{\partial}{\partial x_i} - f(\vec{x}) \frac{\hbar}{i} \frac{\partial}{\partial x_i}$$

$$= \frac{\hbar}{i} \frac{\partial f}{\partial x_i}$$

$$\textcircled{=} -\frac{e}{c} \frac{\hbar}{i} \left( \partial_x A_y - \partial_y A_x \right), \quad \vec{B} = B \hat{z}$$

$$\therefore [\Pi_x, \Pi_y] = \frac{ie\hbar B}{c}$$

(14)

$$(b) \quad H = \frac{1}{2m} (\vec{p} - \frac{e}{c} \vec{A})^2$$

$$= \frac{1}{2m} \vec{\pi}^2 \quad (\pi_z = p_z \quad ; \quad A_z = 0 \quad \therefore \vec{B} = \vec{\nabla} \times \vec{A})$$

$$= \frac{1}{2m} p_z^2 + \frac{1}{2m} (\pi_x^2 + \pi_y^2)$$

$$y := \frac{c}{eB} \pi_x \quad : \quad [y, \pi_y] = i\hbar$$

$$H = \left\{ \frac{1}{2m} p_z^2 \right\} + \underbrace{\left\{ \frac{1}{2m} \pi_y^2 + \frac{1}{2m} \frac{e^2 B^2}{m^2 c^2} y^2 \right\}}_{\text{SHO Ham.}}$$

↓  
free Ham.

"If it looks like a duck,  
if it sounds like a duck,  
it's probably a duck."

$$\therefore \left[ E = \frac{\hbar^2 k^2}{2m} + \hbar \frac{|e|B}{mc} \left( n + \frac{1}{2} \right) \right]$$



## EXTRA 3

(a) Kermack-McCrea thm: (see proof at the end)

$$e^{A+B} = e^{-\frac{1}{2}[A,B]} e^A e^B = e^{\frac{1}{2}[A,B]} e^B e^A$$

if  $[A, [A, B]] = 0 = [B, [A, B]]$ .

$$[a, a^\dagger] = 1$$

$$\therefore [a, [a, a^\dagger]] = 0 = [a^\dagger, [a, a^\dagger]]$$

$$\therefore \Delta(\lambda) = e^{\lambda a^\dagger - \lambda^* a}$$

$$= e^{-\frac{1}{2}[\lambda a^\dagger, -\lambda^* a]} e^{\lambda a^\dagger} e^{-\lambda^* a}$$

$$= e^{\frac{1}{2}|\lambda|^2 [a^\dagger, a]} e^{\lambda a^\dagger} e^{-\lambda^* a}$$

$$= e^{-|\lambda|^2/2} e^{\lambda a^\dagger} e^{-\lambda^* a}$$

$$\Delta(\lambda)|0\rangle = e^{-|\lambda|^2/2} e^{\lambda a^\dagger} e^{-\lambda^* a}|0\rangle \quad \ominus$$

$$a^n|0\rangle = \begin{cases} 0, & n \in \mathbb{N}^+ \\ |10\rangle, & n=0 \end{cases} \Rightarrow e^{-\lambda^* a}|0\rangle = |0\rangle$$

$$\ominus e^{-|\lambda|^2/2} e^{\lambda a^\dagger}|0\rangle$$

$$a^\dagger|0\rangle = \sqrt{1}|1\rangle$$

$$a^{\dagger 2}|0\rangle = \sqrt{1 \times 2}|2\rangle$$

...

$$a^{\dagger n}|0\rangle = \sqrt{n!}|n\rangle$$

$$\therefore e^{\lambda a^\dagger}|0\rangle = \sum_{n \geq 0} \frac{(\lambda a^\dagger)^n}{n!}|0\rangle = \sum_{n \geq 0} \frac{\lambda^n}{n!} \sqrt{n!}|n\rangle$$

$$= \sum_{n \geq 0} \frac{\lambda^n}{\sqrt{n!}}|n\rangle$$

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$$\therefore \Delta(\lambda) |0\rangle = e^{-|\lambda|^2/2} \sum_{n \geq 0} \frac{\lambda^n}{\sqrt{n!}} |n\rangle$$

Now let's see if this is an eigenstate of  $a$ :

$$a(\Delta(\lambda)|0\rangle) = e^{-|\lambda|^2/2} \sum_{n \geq 0} \frac{\lambda^n}{\sqrt{n!}} a|n\rangle \equiv$$

$$a|n\rangle = a \frac{a^{\dagger n}}{\sqrt{n!}} |0\rangle$$

$$= \frac{a^{\dagger n} a + [a, a^{\dagger n}]}{\sqrt{n!}} |0\rangle$$

$$[a, a^{\dagger}] = 1$$

$$[a, a^{\dagger 2}] = a^{\dagger} [a, a^{\dagger}] + [a, a^{\dagger}] a^{\dagger} = 2a^{\dagger}$$

...

$$[a, a^{\dagger n}] = n a^{\dagger n-1} = \frac{\partial}{\partial a^{\dagger}} a^{\dagger n}$$

$$\therefore a|n\rangle = \frac{1}{\sqrt{n!}} \frac{\partial}{\partial a^{\dagger}} a^{\dagger n} |0\rangle$$

$$\therefore a(\Delta(\lambda)|0\rangle) = e^{-|\lambda|^2/2} \sum_{n \geq 0} \frac{\lambda^n}{\sqrt{n!}} \frac{1}{\sqrt{n!}} \frac{\partial}{\partial a^{\dagger}} a^{\dagger n} |0\rangle$$

$$= e^{-|\lambda|^2/2} \frac{\partial}{\partial a^{\dagger}} \sum_{n \geq 0} \frac{(\lambda a^{\dagger})^n}{n!} |0\rangle$$

$$= \frac{\partial}{\partial a^{\dagger}} \left( e^{-|\lambda|^2/2} e^{\lambda a^{\dagger}} \right) |0\rangle$$

$$= \lambda e^{-|\lambda|^2/2} e^{\lambda a^{\dagger}} |0\rangle$$

$$= \lambda e^{-|\lambda|^2/2} e^{\lambda a^{\dagger}} e^{\lambda^* a} |0\rangle$$

$$= \lambda (\Delta(\lambda)|0\rangle)$$

17

$\therefore \Delta(\lambda)|0\rangle$  is the eigenstate of  $a$  w/ eigenvalue  $\lambda$ .

$$\therefore |\lambda\rangle = \Delta(\lambda)|0\rangle \quad \text{qed}$$

$$\begin{aligned} (b) \quad Me^L M^{-1} &= M \left( 1 + L + \frac{1}{2!} L^2 + \dots \right) M^{-1} \\ &= 1 + M L M^{-1} + \frac{1}{2!} M L^2 M^{-1} + \dots \\ &= 1 + M L M^{-1} + \frac{1}{2!} M L M^{-1} M L M^{-1} + \dots \\ &= 1 + (M L M^{-1}) + \frac{1}{2!} (M L M^{-1})^2 + \dots \\ &= e^{M L M^{-1}} \quad \text{qed} \end{aligned}$$

$$\begin{aligned} \mathcal{U}_0(t)^\dagger \Delta(\lambda) \mathcal{U}_0(t) &= e^{iH_0 t/\hbar} e^{\lambda a^\dagger - \lambda^* a} e^{-iH_0 t/\hbar} \\ &= e^{e^{iH_0 t/\hbar} (\lambda a^\dagger - \lambda^* a) e^{-iH_0 t/\hbar}} \\ &= e^{\lambda a^\dagger(t) - \lambda^* a(t)} \end{aligned}$$

$$H_0 = \hbar\omega_0 \left( a^\dagger a + \frac{1}{2} \right)$$

$$[a, H_0] = \hbar\omega_0 [a, a^\dagger a] = \hbar\omega_0 \underbrace{[a, a^\dagger]}_1 a = \hbar\omega_0 a$$

$$\therefore \dot{a} = \frac{\hbar\omega_0 a}{i\hbar} \Rightarrow a(t) = a e^{-i\omega_0 t}$$

$$[a^\dagger, H_0] = \hbar\omega_0 [a^\dagger, a^\dagger a] = \hbar\omega_0 a^\dagger \underbrace{[a^\dagger, a]}_{-1} = -\hbar\omega_0 a^\dagger$$

$$\therefore \dot{a}^\dagger = \frac{-\hbar\omega_0}{i\hbar} a^\dagger \Rightarrow a^\dagger(t) = a^\dagger e^{i\omega_0 t}$$

$$\therefore \mathcal{U}_0(t)^\dagger \Delta(\lambda) \mathcal{U}_0(t) = e^{\lambda e^{i\omega_0 t} a^\dagger - \lambda^* e^{-i\omega_0 t} a}$$

(18)

$$|\alpha(0)\rangle = |\lambda_0\rangle$$

$$|\alpha(t)\rangle = U_0(t) |\lambda_0\rangle$$

$$= U_0(t) \Delta(\lambda_0) |0\rangle$$

$$= U_0(t) \Delta(\lambda_0) U_0^\dagger(t) U_0(t) |0\rangle$$

$$U_0(t) \Delta(\lambda_0) U_0^\dagger(t) = e^{-iH_0 t/\hbar} \Delta(\lambda_0) e^{iH_0 t/\hbar}$$

$$= e^{iH_0(-t)/\hbar} \Delta(\lambda_0) e^{-iH_0(-t)/\hbar}$$

$$= U_0(t)^\dagger \Delta(\lambda) U_0(t) \Big|_{t \rightarrow -t}$$

$$= e^{\lambda e^{-i\omega_0 t} a^\dagger - \lambda^* e^{i\omega_0 t} a}$$

$$U_0(t) |0\rangle = e^{-iH_0 t/\hbar} |0\rangle = e^{-iE_0 t/\hbar} |0\rangle = e^{-i\omega_0 t/2} |0\rangle$$

$$\therefore |\alpha(t)\rangle = e^{\lambda e^{-i\omega_0 t} a^\dagger - \lambda^* e^{i\omega_0 t} a} e^{-i\omega_0 t/2} |0\rangle, \quad \lambda(t) := \lambda e^{-i\omega_0 t}$$

$$= e^{-i\omega_0 t/2} e^{\lambda(t) a^\dagger - \lambda^*(t) a} |0\rangle$$

$$= e^{-i\omega_0 t/2} \Delta(\lambda(t)) |0\rangle$$

$$\boxed{|\alpha(t)\rangle = e^{-i\omega_0 t/2} |\lambda(t)\rangle}$$

$$(c) \quad H_0 = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2$$

$$H_1 = -f x$$

$$\therefore H = H_0 + H_1 = \frac{p^2}{2m} + \frac{1}{2} m \omega^2 x^2 - f x$$

$$[x, H] = \frac{1}{2m} [x, p^2] = \frac{i\hbar p}{m}$$

$$[p, H] = \frac{1}{2} m \omega^2 [p, x^2] - f [p, x] = \frac{m \omega^2}{2} (-2i\hbar x) - f(-i\hbar)$$

$$= -i\hbar m \omega^2 x + i\hbar f$$

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$$\therefore \dot{X} = \frac{1}{i\hbar} \frac{i\hbar P}{m} = \frac{P}{m}$$

$$\dot{P} = \frac{1}{i\hbar} (-i\hbar m\omega^2 X + i\hbar f)$$

$$= -m\omega^2 X + f$$

$$\therefore \ddot{X} = \frac{\dot{P}}{m} = -\omega^2 X + \frac{f}{m}$$

$$\boxed{\ddot{X} + \omega^2 X = \frac{f}{m}}$$

$$(2) \quad |\alpha(t)\rangle = e^{-iH_0 t/\hbar} |\alpha_I(t)\rangle$$

$$\therefore |\alpha_I(t)\rangle = e^{iH_0 t/\hbar} |\alpha(t)\rangle$$

$$i\hbar \frac{\partial}{\partial t} |\alpha_I(t)\rangle = i\hbar \frac{iH_0}{\hbar} e^{iH_0 t/\hbar} |\alpha(t)\rangle + e^{iH_0 t/\hbar} \underbrace{i\hbar \frac{\partial}{\partial t} |\alpha(t)\rangle}_{H |\alpha(t)\rangle}$$

↳ total hamiltonian

$$= e^{iH_0 t/\hbar} (-H_0) |\alpha(t)\rangle + e^{iH_0 t/\hbar} H |\alpha(t)\rangle$$

$$= e^{iH_0 t/\hbar} H_1 |\alpha(t)\rangle$$

$$= e^{iH_0 t/\hbar} H_1 e^{-iH_0 t/\hbar} |\alpha_I(t)\rangle$$

$$= H_I(t) |\alpha_I(t)\rangle \quad \text{qed}$$

$$H_I(t) := e^{iH_0 t/\hbar} H_1 e^{-iH_0 t/\hbar}$$

$$= e^{iH_0 t/\hbar} (-fX) e^{-iH_0 t/\hbar}$$

$$= -f e^{iH_0 t/\hbar} X e^{-iH_0 t/\hbar}$$

$$= -f e^{iH_0 t/\hbar} \sqrt{\frac{\hbar}{2m\omega}} (a^\dagger + a) e^{-iH_0 t/\hbar}$$

$$= -f \underbrace{\sqrt{\frac{\hbar}{2m\omega_0}}}_{=: \alpha_0} \left( \underbrace{e^{iH_0 t/\hbar} a^\dagger e^{-iH_0 t/\hbar}}_{a^\dagger(t)} + \underbrace{e^{iH_0 t/\hbar} a e^{-iH_0 t/\hbar}}_{a(t)} \right)$$

$$= -f \alpha_0 (a^\dagger(t) e^{i\omega_0 t} + a e^{i\omega_0 t}) \text{ from earlier}$$

$$= (-f \alpha_0 e^{i\omega_0 t}) a^\dagger + (-f \alpha_0 e^{-i\omega_0 t}) a$$

$$= g(t) a^\dagger + g(t)^* a$$

$$\therefore \boxed{g(t) = -f \alpha_0 e^{i\omega_0 t}} \quad \text{where } \alpha_0 := \sqrt{\frac{\hbar}{2m\omega_0}}$$

But let's compute  $e^{iH_0 t/\hbar} a^\dagger e^{-iH_0 t/\hbar}$  and  $e^{iH_0 t/\hbar} a e^{-iH_0 t/\hbar}$  by using the Baker-Campbell-Hausdorff formula:

$$e^{iG\lambda} A e^{-iG\lambda} = A + i\lambda [G, A] + \frac{(i\lambda)^2}{2!} [G, [G, A]] + \dots$$

Put  $G = H_0$ ,  $\lambda = t/\hbar$ .

$$H_0 = \hbar\omega_0 \left( a^\dagger a + \frac{1}{2} \right)$$

$$[H_0, a] = \hbar\omega_0 [a^\dagger a, a] = \hbar\omega_0 [a^\dagger, a] a = -\hbar\omega_0 a$$

$$[H_0, [H_0, a]] = [H_0, -\hbar\omega_0 a] = (-\hbar\omega_0)^2 a$$

...

$$[H_0, a^\dagger] = \hbar\omega_0 [a^\dagger a, a^\dagger] = \hbar\omega_0 a^\dagger [a, a^\dagger] = \hbar\omega_0 a^\dagger$$

$$[H_0, [H_0, a^\dagger]] = [H_0, \hbar\omega_0 a^\dagger] = (\hbar\omega_0)^2 a^\dagger$$

...

$$\therefore e^{iH_0 t/\hbar} a^\dagger e^{-iH_0 t/\hbar} = a^\dagger + \left(\frac{it}{\hbar}\right) (\hbar\omega_0) a^\dagger + \frac{1}{2!} \left(\frac{it}{\hbar}\right)^2 (\hbar\omega_0)^2 a^\dagger + \dots$$

$$= a^\dagger \left( 1 + (i\omega_0 t) + \frac{1}{2!} (i\omega_0 t)^2 + \dots \right)$$

$$= a^\dagger e^{i\omega_0 t} \quad \checkmark$$

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$$\begin{aligned}
 e^{iH_0 t/\hbar} a e^{-iH_0 t/\hbar} &= a + \left(\frac{it}{\hbar}\right) (-\hbar\omega) a + \frac{1}{2!} \left(\frac{it}{\hbar}\right)^2 (-\hbar\omega)^2 a + \dots \\
 &= a \left( 1 + (-i\omega t) + \frac{1}{2!} (-i\omega t)^2 + \dots \right) \\
 &= a e^{-i\omega t/\hbar}
 \end{aligned}$$

$$(e) \quad i\hbar \frac{\partial}{\partial t} \mathcal{U}_x(t) = H_x(t) \mathcal{U}_x(t)$$

$$\begin{aligned}
 \mathcal{U}_x(t) &= e^{h(t)a^\dagger - h(t)^* a} e^{i\beta(t)} \quad \text{this is of the form } \Delta(h(t)) \\
 &= e^{-|h(t)|^2/2} e^{h(t)a^\dagger} e^{-h(t)^* a} e^{i\beta(t)}
 \end{aligned}$$

$$\begin{aligned}
 \frac{\partial \mathcal{U}_x(t)}{\partial t} &= -\frac{\partial |h(t)|^2}{\partial t} e^{-|h(t)|^2/2} e^{h(t)a^\dagger} e^{-h(t)^* a} e^{i\beta(t)} \\
 &\quad + e^{-|h(t)|^2/2} \dot{h}(t) a^\dagger e^{h(t)a^\dagger} e^{-h(t)^* a} e^{i\beta(t)} \\
 &\quad + e^{-|h(t)|^2/2} e^{h(t)a^\dagger} (-\dot{h}^*(t) a) e^{-h(t)^* a} e^{i\beta(t)} \\
 &\quad + e^{-|h(t)|^2/2} e^{h(t)a^\dagger} e^{-h(t)^* a} i\dot{\beta}(t) e^{i\beta(t)} \\
 &= \left( -\frac{\partial |h(t)|^2}{\partial t} + \dot{h}(t) a^\dagger + i\dot{\beta}(t) - \dot{h}(t)^* a \right) \mathcal{U}_x(t) \\
 &\quad - \dot{h}^*(t) e^{-|h(t)|^2/2} \underbrace{e^{h(t)a^\dagger} a e^{-h(t)^* a}}_{a e^{h(t)a^\dagger} + [e^{h(t)a^\dagger}, a]} e^{i\beta(t)} \\
 &= \left( -\frac{\partial |h(t)|^2}{\partial t} + \dot{h}(t) a^\dagger + i\dot{\beta}(t) - \dot{h}(t)^* a \right) \mathcal{U}_x(t) \\
 &\quad - \dot{h}^*(t) e^{-|h(t)|^2/2} [e^{h(t)a^\dagger}, a] e^{-h(t)^* a} e^{i\beta(t)} \quad \textcircled{=}
 \end{aligned}$$

$$[a, a^{\dagger n}] = \frac{\partial}{\partial a^\dagger} a^{\dagger n} \quad \text{from earlier}$$

$$\therefore [a, e^{\lambda a^\dagger}] = \sum_n c_n \lambda^n \frac{\partial}{\partial a^\dagger} a^{\dagger n} = \frac{\partial}{\partial a^\dagger} e^{\lambda a^\dagger} = \lambda e^{\lambda a^\dagger}$$

$$\begin{aligned}
& \equiv \left( -\frac{\partial |h(t)|^2}{\partial t} + h(t)a^\dagger - h^*(t)a + i\dot{\beta}(t) \right) \mathcal{U}_x(t) \\
& \quad - h^*(t) e^{-|h(t)|^2/2} (-h(t) e^{h(t)a^\dagger}) e^{-h(t)^* a} e^{i\beta(t)} \\
& = \left( -\frac{\partial |h(t)|^2}{\partial t} + h(t)a^\dagger - h^*(t)a + i\dot{\beta}(t) + h(t)h^*(t) \right) \mathcal{U}_x(t) \\
& = \frac{H_x(t)}{i\hbar} \mathcal{U}_x(t) \\
& = \frac{g(t)a^\dagger + g(t)^* a}{i\hbar} \mathcal{U}_x(t)
\end{aligned}$$

Since  $a$ ,  $a^\dagger$ , and  $1$  are linearly indep., we directly have

$$\begin{aligned}
h(t) &= \frac{g(t)}{i\hbar} \\
-\frac{\partial |h(t)|^2}{\partial t} + i\dot{\beta}(t) + h(t)h^*(t) &= 0
\end{aligned}$$

$$g(t) = -f\pi_0 e^{i\omega_0 t}, \quad \pi_0 = \sqrt{\frac{\hbar}{2m\omega_0}}$$

by just equating the coefficients.

$$(f) \quad |\alpha_x(0)\rangle = |\lambda_0\rangle$$

$$|\alpha_x(t)\rangle = \mathcal{U}_x(t) |\lambda_0\rangle$$

but notice that  $\mathcal{U}_x(t) = e^{i\beta(t)} \Delta(h(t))$ :

$$|\alpha_x(t)\rangle = e^{i\beta(t)} \Delta(h(t)) \Delta(\lambda_0) |0\rangle$$

What to do w/ this operators?

Since  $\Delta$  is a displacement operator, by intuition  $\Delta(\lambda)\Delta(\lambda')$  should be related to  $\Delta(\lambda+\lambda')$ :

$$\begin{aligned}
\Delta(\lambda+\lambda') &= e^{(\lambda+\lambda')a^\dagger - (\lambda^*+\lambda'^*)a} \\
&= e^{(\lambda a^\dagger - \lambda^* a) + (\lambda' a^\dagger - \lambda'^* a)} \\
&= e
\end{aligned}$$



$$[\lambda a^\dagger - \lambda^* a, \lambda' a^\dagger - \lambda'^* a] = -\lambda \lambda'^* \underbrace{[a^\dagger, a]}_{-1} - \lambda^* \lambda' \underbrace{[a, a^\dagger]}_1$$

$$= \lambda \lambda'^* - \lambda^* \lambda'$$

$$= 2i \operatorname{Im} \lambda \lambda'^* \text{ indep of } a \text{ and } a^\dagger$$

$$\therefore [\lambda a^\dagger - \lambda^* a, [\lambda a^\dagger - \lambda^* a, \lambda' a^\dagger - \lambda'^* a]] = 0$$

$$= [\lambda' a^\dagger - \lambda'^* a, [\lambda a^\dagger - \lambda^* a, \lambda' a^\dagger - \lambda'^* a]]$$

$$\therefore \Delta(\lambda + \lambda') = e^{-\frac{1}{2}[\lambda a^\dagger - \lambda^* a, \lambda' a^\dagger - \lambda'^* a]} e^{\lambda a^\dagger - \lambda^* a} e^{\lambda' a^\dagger - \lambda'^* a}$$

$$= e^{-\frac{1}{2} 2i \operatorname{Im} \lambda \lambda'^*} \Delta(\lambda) \Delta(\lambda')$$

$$\therefore \Delta(\lambda) \Delta(\lambda') = e^{i \operatorname{Im} \lambda \lambda'^*} \Delta(\lambda + \lambda')$$

$$\therefore \Delta(h(t)) \Delta(\lambda_0) = e^{i \operatorname{Im} h(t) \lambda_0^*} \Delta(h(t) + \lambda_0)$$

$$\begin{aligned} \therefore |\alpha_{\mathcal{I}}(t)\rangle &= e^{i\beta(t)} e^{i \operatorname{Im} h(t) \lambda_0^*} \Delta(h(t) + \lambda_0) |0\rangle \\ &= e^{i(\beta + \operatorname{Im} h(t) \lambda_0^*)} |h(t) + \lambda_0\rangle \end{aligned}$$

$$|\alpha(t)\rangle = e^{-iH_0 t/\hbar} |\alpha_{\mathcal{I}}(t)\rangle$$

$$= e^{i(\beta + \operatorname{Im} h(t) \lambda_0^*)} \mathcal{U}_0(t) \Delta(h(t) + \lambda_0) |0\rangle$$

$$= e^{i(\beta + \operatorname{Im} h(t) \lambda_0^*)} \underbrace{\mathcal{U}_0(t) \Delta(\lambda') \mathcal{U}_0(t)^\dagger}_{e^{\lambda' e^{-i\omega_0 t} a^\dagger - \lambda'^* e^{i\omega_0 t} a}} \underbrace{\mathcal{U}_0(t) |0\rangle}_{e^{-iE_0 t/\hbar} |0\rangle}, \lambda' := h(t) + \lambda_0$$

$$= e^{i(\beta + \operatorname{Im} h(t) \lambda_0^*)} \Delta(\lambda' e^{-i\omega_0 t}) |0\rangle$$

$$= e^{i\gamma(t)} |\lambda(t)\rangle$$

$$\text{where } \lambda(t) = \lambda' e^{-i\omega_0 t}$$

$$\boxed{\lambda(t) = (h(t) + \lambda_0) e^{-i\omega_0 t}}$$

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$$\dot{h}(t) = \frac{g(t)}{i\hbar} = \frac{1}{i\hbar} (-f x_0 e^{i\omega_0 t})$$

$$\therefore h(t) = \frac{-f x_0}{i\hbar} \frac{e^{i\omega_0 t}}{i\omega_0} \quad \text{up to some additive const.}$$

$$\boxed{h(t) = \frac{f x_0}{\hbar \omega_0} e^{i\omega_0 t}}$$

$$\lambda(t) = \left( \frac{f x_0}{\hbar \omega_0} e^{i\omega_0 t} + \lambda_0 \right) e^{-i\omega_0 t}$$

$$= \frac{f x_0}{\hbar \omega_0} + \lambda_0 e^{-i\omega_0 t}$$

Since  $\lambda_0$  is a complex number, we can write it as

$$\lambda_0 = A + iB$$

Then

$$\lambda(t) = \frac{f x_0}{\hbar \omega_0} + (A + iB)(\cos \omega_0 t - i \sin \omega_0 t)$$

$$= \underbrace{\frac{f x_0}{\hbar \omega_0} + A \cos \omega_0 t + B \sin \omega_0 t}_{\text{real}} + i(\dots)$$

$$x(t) := \sqrt{\frac{2\hbar}{m\omega_0}} \operatorname{Re} \lambda(t) = 2 \sqrt{\frac{\hbar}{2m\omega_0}} \operatorname{Re} \lambda(t)$$

$$= 2 x_0 \left( \frac{f x_0}{\hbar \omega_0} + A \cos \omega_0 t + B \sin \omega_0 t \right)$$

$$= f \frac{2 x_0^2}{\hbar \omega_0} + A' \cos \omega_0 t + B' \sin \omega_0 t$$

$$\underbrace{\frac{2}{\hbar \omega_0} \frac{\hbar}{2m\omega_0}}$$

$$= \frac{f}{m\omega_0^2} + A' \cos \omega_0 t + B' \sin \omega_0 t$$

Recall the equation of motion:

$$\ddot{x} + \omega_0^2 x = \frac{f}{m}$$

From Phys209, we know that  $\exists$  two types of solutions here:

$$\ddot{x}_c + \omega_0^2 x_c = 0 \quad \text{complementary solution} \leftrightarrow \text{homogeneous eqn}$$

$$\ddot{x}_p + \omega_0^2 x_p = \frac{f}{m} \quad \text{particular solution} \leftrightarrow \text{inhomo. eqn.}$$

The complementary solution is apparently

$$x_c(t) = C \cos \omega_0 t + D \sin \omega_0 t$$

Since the force is const, so should be the particular solution:

$$x_p = K, \quad \dot{x}_p = \ddot{x}_p = 0$$

$$\omega_0^2 K = \frac{f}{m} \quad \therefore K = \frac{f}{m\omega_0^2}$$

$$\therefore x(t) = \frac{f}{m\omega_0^2} + C \cos \omega_0 t + D \sin \omega_0 t$$

which is exactly  $\sqrt{2\hbar/m\omega_0} \operatorname{Re} \lambda(t)$ .

## EXTRA 3 (Proof of the thm)

(a) Kerrick-Melrose thm For  $[A, [A, B]] = 0 = [B, [A, B]]$ ,

$$e^{A+B} = e^{-\frac{1}{2}[A, B]} e^A e^B \quad \text{"AB ordered"}$$

$$= e^{-\frac{1}{2}[A, B]} e^B e^A \quad \text{"BA ordered"}$$

Proof. Let  $a$  and  $b$  denote the 'scalar' operators that correspond to  $A$  and  $B$ , resp., that is,  $ab = ba$ . Let

$$f(a, b)_{AB} = f(a \rightarrow A, b \rightarrow B) \text{ in the order } AB$$

For ex, if we have  $f(a, b)_{AB} = e^{a+b} = e^a e^b$ , then

$$f(a, b)_{AB} = e^A e^B \quad \text{et.} \quad f(a, b)_{BA} = e^B e^A$$

Let

$$F := e^{A+B}$$

which we also want to be equal to  $f(a, b)_{AB}$ .  
Then we see that

$$\frac{\partial F}{\partial A} = \frac{\partial F}{\partial B} = F$$

$$\therefore \frac{\partial f}{\partial a} = \frac{\partial f}{\partial b} = f \quad \therefore f(a, b) = C e^{a+b}$$

This means that  $C$  should satisfy

$$C e^A e^B = e^{A+B}$$

where we tacitly assumed that  $C$  commutes w/ both  $A$  and  $B$ .

The standard trick in dealing w/ the algebra of nested commutators — as we have learned in Baker-Hausdorff formula — is to parametrize the exponentials:

$$C(\lambda) e^{\lambda A} e^{\lambda B} = e^{\lambda(A+B)} \quad | \leftarrow e^{-\lambda B}$$

$$C(\lambda) e^{\lambda A} = e^{\lambda(A+B)} e^{-\lambda B} \quad | \leftarrow e^{-\lambda A}$$

$$C(\lambda) = e^{\lambda(A+B)} e^{-\lambda B} e^{-\lambda A}$$

$$C(0) = 1$$

$$\begin{aligned} \frac{dC(\lambda)}{d\lambda} &= (A+B) e^{\lambda(A+B)} e^{-\lambda B} e^{-\lambda A} \\ &\quad + e^{\lambda(A+B)} (-B) e^{-\lambda B} e^{-\lambda A} \\ &\quad + e^{\lambda(A+B)} e^{-\lambda B} (-A) e^{-\lambda A}, \quad [e^{\lambda(A+B)}, (A+B)] = 0 \end{aligned}$$

$$= e^{\lambda(A+B)} (A+B) e^{-\lambda B} e^{-\lambda A}$$

$$- e^{\lambda(A+B)} B e^{-\lambda B} e^{-\lambda A}$$

$$- e^{-\lambda(A+B)} e^{-\lambda B} A e^{-\lambda A}$$

$$= e^{\lambda(A+B)} [A, e^{-\lambda B}] e^{-\lambda A}$$

$$[A, e^{-\lambda B}] = \sum_n \frac{(-\lambda)^n}{n!} [A, B^n]$$

$$[A, B^2] = B[A, B] + [A, B]B = 2B[A, B] \quad (\text{recall assumption})$$

$$[A, B^3] = \underbrace{B[A, B^2]}_{2B[A, B]} + [A, B]B^2 = 3B^2[A, B]$$

$$[A, e^{-\lambda B}] = \sum_n c_n (-\lambda)^n n B^{n-1} [A, B]$$

$$= [A, B] \sum_n c_n (-\lambda)^n n B^{n-1}$$

$$= [A, B] \frac{\partial}{\partial B} \sum_n c_n (-\lambda)^n B^n$$

$$= [A, B] \frac{\partial}{\partial B} e^{-\lambda B}$$

$$= -\lambda [A, B] e^{-\lambda B}$$

$$= -\lambda e^{-\lambda B} [A, B]$$

$$\therefore \frac{dC(\lambda)}{d\lambda} = e^{\lambda(A+B)} (-\lambda e^{-\lambda B} [A, B]) e^{-\lambda A}$$

$$= -\lambda [A, B] e^{\lambda(A+B)} e^{-\lambda B} e^{-\lambda A}$$

$$= -\lambda [A, B] C(\lambda)$$

Since  $C$  commutes w/  $A$  and  $B$ , it also commutes w/  $[A, B]$ , so we can easily integrate it.

$$\frac{dC(\lambda)}{d\lambda} = -\lambda [A, B] C(\lambda)$$

$$\ln C(\lambda) = -\frac{\lambda^2}{2} [A, B] + \ln C(0)$$

$$C(\lambda) = \underbrace{C(0)}_1 e^{-\frac{\lambda^2}{2} [A, B]}$$

$$= e^{-\frac{\lambda^2}{2} [A, B]}$$

(29)

Finally, by taking  $\lambda=1$ ,

$$e^{A+B} = e^{-\frac{1}{2}[A,B]} e^A e^B$$

and since  $A \leftrightarrow B$  implies  $[A,B] \rightarrow -[A,B]$ ,

$$e^{A+B} = e^{\frac{1}{2}[A,B]} e^B e^A \quad \text{qed.}$$

①

## EXTRA 4

$$(a) \quad H_0 = \frac{\vec{L}^2}{2I}$$

$$\vec{L}^2 |lm\rangle = \hbar^2 l(l+1) |lm\rangle$$

$$\psi_{lm}(\vec{r}) = \langle \hat{n} | lm \rangle = \langle \theta, \varphi | lm \rangle =: Y_{lm}(\theta, \varphi)$$

$$E_l = \frac{\hbar^2 l(l+1)}{2I}$$

$\exists$  2 quantum #s that describe the dynamics,  $l$  and  $m$ :

$$l \in \mathbb{N}$$

$$m = -l : l \Rightarrow 2l+1 \text{ values } \forall l$$

Notice that for all  $l$ ,  $\exists (2l+1)$ -many  $m$  values but the energy eigenvalues are indep. of  $m$ , so the degeneracy is  $2l+1$ .

$$(b) \quad H_1 = \frac{L_x^2 + L_y^2}{2I_1} + \frac{L_z^2}{2I_2}$$

$\exists$  two ways to proceed. I will do one of them:

$$L_x^2 + L_y^2 = L^2 - L_z^2 \quad \left( = \frac{1}{2} (L_+ L_- + L_- L_+) \right)$$

$\downarrow$   
2<sup>nd</sup> way

$$H_1 = \frac{L^2}{2I} - \frac{1}{2} \left( \frac{1}{I_1} - \frac{1}{I_2} \right) L_z^2$$



②

Since  $[L^2, L_z] = 0$ , and since  $|lm\rangle$  is eigenstate of both of them, the spherical harmonics is still the eigenfunction. But the energy eigenvalues and the degeneracy ~~will~~ need careful examination:

$$L^2 \rightarrow \hbar^2 l(l+1)$$

$$L_z \rightarrow \hbar m$$

$$\therefore E_{lm} = \frac{\hbar^2 l(l+1)}{2I_1} - \frac{1}{2} \left( \frac{1}{I_1} - \frac{1}{I_2} \right) \hbar^2 m^2$$

Again the dynamics depend on two quantum numbers,  $l$  and  $m$ , but the energy eigenvalues also depend on  $l$  and  $m$  explicitly.

Intuitively, we expect the greater the number of quantum #s the energy depends on, the smaller the degeneracy. Yes,  $\exists$  still  $(2l+1)$ -many  $m$  values for each  $l$ , we have a different energy for each  $|m|$ . That is, the degeneracy is significantly lifted: we have 2 degeneracies left —  $\pm m$ .

③

EXTRA 5

3.5

- Method 1: Use explicit forms of  $S_n$  and  $S_2$ .
- Method 2:

Cayley-Hamilton thm      Any given square matrix satisfies its scalar eqn.

Proof. (See your Math 260 notes.)

∴ Cayley-Hamilton thm says that

$$\prod_{i=1}^N (A - \lambda_i) = 0$$

where  $A$  is an  $N \times N$  matrix and the  $\lambda_i$  are the eigenvalues of  $A$ .

Think about it.

(4)

3.14

$$(G_i)_{jk} = -i\hbar \varepsilon_{ijk}$$

$$([G_i, G_j])_{mn} = (G_i G_j)_{mn} - (G_j G_i)_{mn}$$

$$= (G_i)_{mk} (G_j)_{kn} - (G_j)_{mk} (G_i)_{kn}$$

$$= (-i\hbar \varepsilon_{imk}) (-i\hbar \varepsilon_{jkn}) - (-i\hbar \varepsilon_{jmk}) (-i\hbar \varepsilon_{ikn})$$

$$= (-i\hbar)^2 (\varepsilon_{imk} \varepsilon_{jkn} - \varepsilon_{jmk} \varepsilon_{ikn})$$

$$= (-i\hbar)^2 (\delta_{in} \delta_{mj} - \delta_{ij} \delta_{mn}) - (\delta_{jn} \delta_{mi} - \delta_{ji} \delta_{mn})$$

$$= (-i\hbar)^2 (\delta_{in} \delta_{mj} - \cancel{\delta_{ij} \delta_{mn}} - \delta_{im} \delta_{jn} + \cancel{\delta_{ij} \delta_{mn}})$$

$$= (-i\hbar)^2 (\delta_{in} \delta_{mj} - \delta_{im} \delta_{jn})$$

$$= (-i\hbar)^2 \varepsilon_{ijk} \underbrace{\varepsilon_{nmk}}_{-\varepsilon_{mnk} = -\varepsilon_{kmn}} \text{ by trial and error}$$

$$= i\hbar \varepsilon_{ijk} (-i\hbar \varepsilon_{kmn})$$

$$= i\hbar \varepsilon_{ijk} (G_k)_{mn}$$

$$\therefore [G_i, G_j] = i\hbar \varepsilon_{ijk} G_k \quad \text{qed}$$

(5)

Matrix representation of the  $J_i$  for  $j=1$ :

$$|11\rangle \doteq \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad |10\rangle \doteq \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad |1-1\rangle \doteq \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$J_z |jm\rangle = \hbar m |jm\rangle$$

$$\therefore \langle jm' | J_z | jm \rangle = \hbar m \delta_{m'm}$$

$$J_{\pm} |jm\rangle = \hbar \sqrt{j(j+1) - m(m\pm 1)} |jm\pm 1\rangle$$

$$\therefore \langle jm' | J_{\pm} | jm \rangle = \hbar \sqrt{j(j+1) - m(m\pm 1)} \delta_{m'm\pm 1}$$

$$\therefore (J_z)_{m'm} = \hbar m \delta_{m'm}$$

$$(J_+)_{m'm} = \hbar \sqrt{2 - m(m+1)} \delta_{m'm+1}$$

$$(J_-)_{m'm} = \hbar \sqrt{2 - m(m-1)} \delta_{m'm-1}$$

$$\therefore J_z \doteq \hbar \begin{pmatrix} 1 & & \\ & 0 & \\ & & -1 \end{pmatrix}$$

$$J_+ \doteq \hbar \begin{pmatrix} 0 & \sqrt{2} & 0 \\ & 0 & \sqrt{2} \\ & & 0 \end{pmatrix}, \quad J_- \doteq \hbar \begin{pmatrix} 0 & & \\ \sqrt{2} & 0 & \\ 0 & \sqrt{2} & 0 \end{pmatrix}$$

$$J_x = \frac{J_+ + J_-}{2} \doteq \frac{\hbar}{2} \begin{pmatrix} 0 & \sqrt{2} & 0 \\ \sqrt{2} & 0 & \sqrt{2} \\ 0 & \sqrt{2} & 0 \end{pmatrix} = \frac{\hbar}{\sqrt{2}} \begin{pmatrix} 0 & 1 & 0 \\ 1 & 0 & 1 \\ 0 & 1 & 0 \end{pmatrix}$$

$$J_y = \frac{J_+ - J_-}{2i} = \frac{\hbar}{2i} \begin{pmatrix} 0 & \sqrt{2} & 0 \\ -\sqrt{2} & 0 & \sqrt{2} \\ 0 & -\sqrt{2} & 0 \end{pmatrix} = \frac{i\hbar}{\sqrt{2}} \begin{pmatrix} 0 & -1 & 0 \\ 1 & 0 & -1 \\ 0 & 1 & 0 \end{pmatrix}$$

⑥

Matrix representation of  $G_i$ :

$$(G_1)_{jk} = -i\hbar \begin{matrix} \epsilon_{1k} \\ 23 \\ 32 \end{matrix}$$

$$(G_2)_{jk} = -i\hbar \begin{matrix} \epsilon_{2k} \\ 31 \\ 13 \end{matrix}$$

$$(G_3)_{jk} = -i\hbar \begin{matrix} \epsilon_{3k} \\ 12 \\ 21 \end{matrix}$$

$$\therefore G_1 = -i\hbar \begin{pmatrix} 0 & 0 & 0 \\ 0 & 0 & 1 \\ 0 & -1 & 0 \end{pmatrix}$$

$$G_2 = -i\hbar \begin{pmatrix} 0 & 0 & -1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}$$

$$G_3 = -i\hbar \begin{pmatrix} 0 & 1 & 0 \\ -1 & 0 & 0 \\ 0 & 0 & 0 \end{pmatrix}$$

Since we are asked to relate  $G_i$  to  $J_i$  by a similarity transformation in the basis where  $J_3$  is diagonal, if we can find the matrix that diagonalizes  $G_3$ , we are done.

Eigenvalues of  $G_3$ :

$$\begin{vmatrix} -\lambda & 1 & 0 \\ -1 & -\lambda & 0 \\ 0 & 0 & -\lambda \end{vmatrix} = -\lambda(\lambda^2 + 1) = 0$$

$$\therefore \lambda = -i\hbar \{0, \pm i\} = \hbar \{0, \pm 1\} \quad \text{as expected } \because \mathcal{U}^\dagger G_3 \mathcal{U} = J_3$$

$\downarrow$   
diag.

⑦

Eigenvectors of  $G_3$ :

$$\begin{pmatrix} -\lambda & 1 & 0 \\ -1 & -\lambda & 0 \\ 0 & 0 & -\lambda \end{pmatrix} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 0 \end{pmatrix}$$

$$\lambda \neq 0: \quad \left. \begin{array}{l} c = 0 \\ -\lambda a + b = 0 \Rightarrow b = \lambda a \end{array} \right\} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 1 \\ \pm i \\ 0 \end{pmatrix} \frac{1}{\sqrt{2}}$$

$$\lambda = 0: \quad \left. \begin{array}{l} c \neq 0 \text{ (free)} \\ a = 0 \\ b = 0 \end{array} \right\} \begin{pmatrix} a \\ b \\ c \end{pmatrix} = \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}$$

$$\text{let } \hat{a}_{\pm} := \frac{\hat{x} \pm i\hat{y}}{\sqrt{2}}$$

$$\hat{a}_0 := \hat{z}$$

$$\text{where } \hat{x} := \begin{pmatrix} 1 \\ 0 \\ 0 \end{pmatrix}, \quad \hat{y} := \begin{pmatrix} 0 \\ 1 \\ 0 \end{pmatrix}, \quad \hat{z} := \begin{pmatrix} 0 \\ 0 \\ 1 \end{pmatrix}.$$

this will be useful later.

Now, let's consider the transformation  $\vec{v} \rightarrow \vec{v} + \hat{n} \delta\varphi \times \vec{v}$  before the significance of  $U$ , which looks like

$$U = (\hat{a}_+ \hat{a}_0 \hat{a}_-) = \begin{pmatrix} 1/\sqrt{2} & 0 & 1/\sqrt{2} \\ i/\sqrt{2} & 0 & -i/\sqrt{2} \\ 0 & 1 & 0 \end{pmatrix}$$

(check  $U^\dagger G_3 U = J_3$ .)

⑧

Now,

$$\psi_i \rightarrow \psi_i + \epsilon_{ijk} \hat{n}_j \delta\varphi \psi_k$$

$$\rightarrow \psi_i + \frac{(G_i)_{jk}}{-i\hbar} \hat{n}_j \delta\varphi \psi_k$$

$$\rightarrow \psi_i + \frac{i}{\hbar} \delta\varphi \underbrace{\hat{n}_j G_{jk}^i}_{\hat{n} \cdot \vec{G}^i} \psi_k$$

(compare:  $a_i b_j A_{ij} = \vec{a} \cdot \vec{A} \vec{b}$ )

$$\rightarrow \psi_i + \frac{i}{\hbar} \delta\varphi \underbrace{\hat{n} \cdot \vec{G}^i}_{\text{how to interpret this?}} \psi_k$$

how to ~~interpret~~ this?

Instead, consider this:

$$\psi_i \rightarrow \psi_i + \underbrace{(-\epsilon_{jik})}_{-\frac{G_{jk}^i}{-i\hbar}} \hat{n}_j \delta\varphi \psi_k$$

$$\rightarrow \psi_i - \frac{i}{\hbar} \delta\varphi \underbrace{\hat{n}_j G_{jk}^i}_{(\hat{n} \cdot \vec{G})_{ik}} \psi_k$$

$(\hat{n} \cdot \vec{G})_{ik}$ : much more meaningful

$$\rightarrow \psi_i - \frac{i}{\hbar} \delta\varphi (G_n \vec{G})_i, \quad G_n := \hat{n} \cdot \vec{G}$$

$$\rightarrow \left( \delta_{ij} - \frac{i}{\hbar} \delta\varphi (G_n)_{ij} \right) \psi_k$$

$$\therefore \vec{\psi} \rightsquigarrow e^{-\frac{i}{\hbar} \delta\varphi G_n} \vec{\psi}$$

(9)

Recall, from linear algebra that

$$e^{iA} = e^{U^\dagger D U} = U^\dagger e^D U$$

where  $A$  is any square matrix and  $D$  is the diagonal matrix  $D = \text{diag}(a_1, a_2, \dots, a_n)$  where  $a_i$  are the eigenvalues of  $A$ .

Put  $A \rightarrow G_n$

$D \rightarrow J_n$

though this will work only for  $\hat{n} = \hat{z}$  ( $\because J_x$  or  $J_y$  is not diag.)

$$e^{-\frac{i}{\hbar} 84 G_3} = U^\dagger e^{-\frac{i}{\hbar} 84 J_{0z}} U$$

where  $U$  is the very same matrix that diagonalizes  $G_3$ .

Now the phys. significance of  $U$ : Before that, maybe I should mention about the hint at the end—photon spin.

From particle phys, we know that the "wave function" of the photon field is given by  $A_\mu$ , the usual 4-potential. Apparently, this object has 4 degrees of freedom but we know that the physical degrees of freedom of the photon is 2 (to wit,  $\vec{E}$  and  $\vec{B}$  fields). Due to the fact that the photon field is massless,



(10)

its spin degeneracy ( $2s+1 = 2(1)+1 = 3$ ) reduces to 2. The physical realization of this is the 2 polarization states of light.

Recall the polarization: since  $|\vec{E}| = c|\vec{B}|$  for a 'free' light wave, the direction of  $\vec{E}$  determines the polarization state. If

$$\vec{E} = |\vec{E}| \hat{n} \quad \text{or} \quad \vec{E} = |\vec{E}| \hat{y}$$

it is linearly polarized. If

$$\vec{E} = |\vec{E}| \frac{\hat{n} \pm i\hat{y}}{\sqrt{2}}$$

then <sup>circular</sup> it is RH (+) or LH (-) polarized.

If we treat the  $\vec{u}$  vector above as the propagation vector, then we see that  $u$  creates a transition b/w circular and linear polarizations (just because the  $u$  matrix has components  $(\hat{a}_+, \hat{a}_0, \hat{a}_-)$ ).

---

Since this part of the problem is a bit problematic, I've looked it up on the internet. But I couldn't find any satisfactory answer. The explanation above is mine and open to discussion.

(11)

3.15

$$(a) \quad J_{\pm} := J_x \pm iJ_y$$

$$\therefore J_x = \frac{J_+ + J_-}{2}$$

$$J_y = \frac{J_+ - J_-}{2i}$$

$$J_x^2 + J_y^2 = \frac{(J_+ + J_-)(J_+ + J_-)}{4} - \frac{(J_+ - J_-)(J_+ - J_-)}{4}$$

$$= \frac{1}{4} \left( \cancel{J_+^2} + \cancel{J_-^2} + J_+ J_- + J_- J_+ - \cancel{J_+^2} - \cancel{J_-^2} + J_+ J_- + J_- J_+ \right)$$

$$= \frac{1}{2} (J_+ J_- + J_- J_+)$$

$$[J_+, J_-] = [J_x + iJ_y, J_x - iJ_y]$$

$$= -i[J_x, J_y] + i[J_y, J_x]$$

$$= -2i \underbrace{[J_x, J_y]}_{i\hbar J_z}$$

$$= 2\hbar J_z$$

$$\begin{aligned} \therefore J^2 &= J_x^2 + J_y^2 + J_z^2 = \frac{1}{2} (J_+ J_- + J_- J_+) + J_z^2 \\ &= \frac{1}{2} (J_+ J_- + J_- J_+ + \underbrace{[J_-, J_+]}_{-2\hbar J_z}) + J_z^2 \end{aligned}$$

12

$$J^2 = J_+ J_- - \hbar J_z + J_z^2 \quad \text{qed}$$

$$(b) \quad J_- |jm\rangle = c_- |jm\rangle \quad | \quad |^2$$

$$\langle jm | \underbrace{J_+ J_-}_{J^2 + \hbar J_z - J_z^2} | jm \rangle = |c_-|^2 \underbrace{\langle jm | jm \rangle}_1$$

$$\therefore |c_-|^2 = \langle jm | J^2 - J_z^2 + \hbar J_z | jm \rangle$$

$$= \hbar^2 j(j+1) - \hbar^2 m^2 + \hbar \hbar m$$

$$= \hbar^2 (j(j+1) - m(m-1))$$

Assume  $c_- \in \mathbb{R}^+$ :

$$\boxed{c_- = \hbar \sqrt{j(j+1) - m(m-1)}}$$

(13)

3.17

(a) Since the eigenfunctions of  $L^2$  are the spherical harmonics, if we can represent  $x$ ,  $y$ , and  $z$  in terms of linear combinations of  $Y_{lm}$ , then we are done. See [1]:

$$x = \sqrt{\frac{4\pi}{3}} y_{1-1}$$

$$y = \sqrt{\frac{4\pi}{3}} y_{11}$$

$$z = \sqrt{\frac{4\pi}{3}} y_{10}$$

$$\therefore \psi(\vec{r}) = (x + y + 3z) f(r)$$

$$= \sqrt{\frac{4\pi}{3}} (y_{1-1} + y_{11} + 3y_{10}) f(r)$$



It is clear that  $\boxed{l=1}$ .

(b) Since probability is a relativistic business, let's directly focus on the  $Y_{lm}$ 's:

$$\psi \propto 1 y_{1-1} + 1 y_{11} + 3 y_{10}$$

$$\therefore \left. \begin{aligned} P(m_l = -1) &= N 1^2 = N \\ P(m_l = 1) &= N 1^2 = N \\ P(m_l = 0) &= N 3^2 = 9N \end{aligned} \right\} \sum_{m_l} P(m_l) = 1 \Rightarrow N = \frac{1}{11}$$

(14)

(c) As a common knowledge, we know that the ~~radial~~ angular part of all wavefunctions under ~~the~~ some spherically-sym potential is the spherical harmonics.

$$\psi(\vec{r}) = \sqrt{\frac{4\pi}{3}} (\gamma_{1-1} + \gamma_{11} + 3\gamma_{10}) f(r)$$

Since the Laplacian is a linear operator, you can collect all the spherical harmonics under a collective  $m$ :

$$\gamma_{1m} := \sqrt{\frac{4\pi}{3}} (\gamma_{1-1} + \gamma_{11} + 3\gamma_{10})$$

so

$$\psi(\vec{r}) = f(r) \gamma_{1m}$$

We can do this also because the  $l$  value is unique.

Now let's "solve" the Schr. equation:

$$H\psi = E\psi$$

$$\left( -\frac{\hbar^2}{2m} \nabla^2 + V(r) \right) \psi = E\psi$$

If you know the trick to deal w/ the Laplacian, then you will realize this:

$$\frac{\vec{p}^2}{2m} = \frac{\vec{p}_r^2}{2m} + \frac{\vec{L}^2}{2mr^2}$$

where  $\vec{p}_r = \frac{\hbar}{i} \left( \frac{\partial}{\partial r} + \frac{1}{r} \right)$  and  $\vec{L}^2 \rightarrow \hbar^2 l(l+1)$  effectively.

(15)

(I recall this happens only in spherical coordinates in 3D.)

So we have

$$\left( \frac{p_r^2}{2m} + \frac{\hbar^2 l(l+1)}{2mr^2} + V(r) \right) \Big|_{l \rightarrow 1} f(r) Y_{1m}(\Omega) = E f(r) Y_{1m}(\Omega)$$

Since the angular derivations have been handled, we can cancel out  $Y_{1m}$ 's:

$$\left( -\frac{\hbar^2}{2m} \left( \frac{\partial}{\partial r} + \frac{1}{r} \right)^2 + \frac{\hbar^2 l(l+1)}{2mr^2} + V(r) \right) \Big|_{l \rightarrow 1} f(r) = E f(r)$$

$$\left( \frac{\partial}{\partial r} + \frac{1}{r} \right) \left( \frac{\partial}{\partial r} + \frac{1}{r} \right) f$$

$$= \left( \frac{\partial}{\partial r} + \frac{1}{r} \right) \left( f' + \frac{f}{r} \right) = f'' + \frac{f'}{r} - \frac{f}{r^2} + \frac{f'}{r} + \frac{f}{r^2}$$

$$= f'' + \frac{2f'}{r}, \quad ' := \frac{\partial}{\partial r}$$

$$-\frac{\hbar^2}{2m} \left( f'' + \frac{2f'}{r} \right) + \frac{\hbar^2}{mr^2} f + V f = E f \quad \Big| \quad \frac{1}{f}, \quad f \neq 0 \text{ we know}$$

$$V = E - \frac{\hbar^2}{mr^2} + \frac{\hbar^2}{2m} \left( \frac{f''}{f} + \frac{2f'}{rf} \right)$$

[1] "Spherical harmonics," (n.d.) Retrieved from

[cs.dartmouth.edu/~wjarosz/publications/dissertation/appendix B.pdf](http://cs.dartmouth.edu/~wjarosz/publications/dissertation/appendix B.pdf)

(16)

3.18

$$|\psi\rangle = |lm\rangle$$

$$L_x = \frac{L_+ + L_-}{2}, \quad L_y = \frac{L_+ - L_-}{2i}$$

$$L_{\pm} |lm\rangle \propto |lm \pm 1\rangle$$

$$\therefore \begin{cases} \langle L_x \rangle = A \langle lm | lm+1 \rangle + B \langle lm | lm-1 \rangle = 0 \\ \langle L_y \rangle = A' \langle lm | lm+1 \rangle + B' \langle lm | lm-1 \rangle = 0 \end{cases} \left. \vphantom{\begin{matrix} \langle L_x \rangle \\ \langle L_y \rangle \end{matrix}} \right\} \boxed{\langle L_x \rangle = \langle L_y \rangle = 0} \quad \text{qed}$$

where  $A, A', B,$  and  $B'$  are some coefficients.

$$L_x^2 = \frac{1}{4} (L_+^2 + L_-^2 + L_+ L_- + L_- L_+)$$

$$L_y^2 = -\frac{1}{4} (L_+^2 + L_-^2 - L_+ L_- - L_- L_+)$$

but effectively,  $L_{\pm}^2$  terms drop, so we have

$$L_x^2 \equiv \frac{1}{4} (L_+ L_- + \underbrace{[L_-, L_+]}_{-2\hbar L_z} + L_- L_+)$$

$$\equiv \frac{1}{2} (L_+ L_- - \hbar L_z)$$

$$\equiv \frac{1}{2} ((L^2 + \hbar L_z - L_z^2) - \hbar L_z)$$

$$\equiv \frac{1}{2} (L^2 - L_z^2)$$

$$L_y^2 \equiv \frac{1}{4} (L_+ L_- + L_- L_+)$$

$$\equiv L_x^2$$

$$\equiv \frac{1}{2} (L^2 - L_z^2)$$

$$\therefore \boxed{\langle L_x^2 \rangle = \langle L_y^2 \rangle = \frac{1}{2} (\hbar^2 l(l+1) - \hbar^2 m^2)}$$

qed

(17)

Semi-classical interpretation: From statistical mechanics, the average of a quantity from a single system measured "lots" of times equals that from "lots" of ~~sys~~ identically prepared systems measured once for each system. In either case, we have the following: Due to randomness (or, better, uncertainty) in that we don't know  $L_x$  and  $L_y$  values, they will cancel out (I mean,  $L_x$  will cancel among themselves, and so will  $L_y$ ). This can be stated also in terms of ~~any~~ symmetry: Whatever "torque" has imparted the initial angular momentum to the system, in the long-term average system preferentially picks a symmetry axis, say  $z$  (this could be  $x$  or  $y$ , as well). Since there had been no torque in the two other directions, we expect that the components of the angular mom. in those directions vanish.

Now, this perfectly explains why  $\langle L_x \rangle = \langle L_y \rangle = 0$  semi-classically, but what do we do w/  $\langle L_x^2 \rangle$  and  $\langle L_y^2 \rangle$ ? They are related to the fluctuations in the angular momentum components — that is, the RMS errors in your measurement.



(18)

Recall the uncertainty is just standard deviation or the error, statistically speaking. So we have nonzero

$\sqrt{\langle \Delta L_x^2 \rangle}$  and  $\sqrt{\langle \Delta L_y^2 \rangle}$ . They should be nonzero again from a statistical-mechanical point of view — "everything fluctuates."

So the long story short:

•  $\langle L_x \rangle = \langle L_y \rangle = 0$   $\because$  perfect cancellation of random (uncertain) components of  $\vec{L}$ .

•  $\langle L_x^2 \rangle = \langle L_y^2 \rangle \neq 0$   $\because$  errors / deviations / fluctuations in the measurement / sys.

(due to symmetry,  $\langle L_x^2 \rangle = \langle L_y^2 \rangle$  is no coincidence.)

(19)

## EXTRA 6

Recall that the rotation operator in the Hilbert space is given by

$$D_n^J(\theta) = e^{-i\vec{J} \cdot \hat{n} \theta / \hbar}$$

The minus sign in the exponent will be important.

$$\begin{aligned}
 (a) \quad J_3 |R, J\rangle &= J_3 e^{iJ_3 \theta / \hbar} |J, J\rangle \\
 &= e^{iJ_3 \theta / \hbar} J_3 |J, J\rangle \rightarrow \text{this should be clear} \\
 &= e^{iJ_3 \theta / \hbar} \hbar m |J, J\rangle \Big|_{m \rightarrow J} \\
 &= \hbar J e^{iJ_3 \theta / \hbar} |J, J\rangle \\
 &= \hbar J |R, J\rangle
 \end{aligned}$$

This tells you something quite obvious: If you rotate the system about the 3<sup>rd</sup> axis, the 3<sup>rd</sup> component of the angular momentum will be conserved.

(2)

(b) In the usual 3D space, vectors transform as

$$\vec{v} \rightarrow R \vec{v}$$

and the matrices as

$$A \rightarrow R^T A R$$

under rotation. (The latter follows from this:

the scalars are invariant under rotation, so

$$\vec{v} \cdot A \vec{u} \rightarrow \vec{v} \cdot R^T A R \vec{u}.)$$

Therefore in the language of quantum mechanics, we have

$$|\alpha\rangle \rightarrow D(R) |\alpha\rangle$$

$$A \rightarrow D(R)^\dagger A D(R)$$

Therefore, in order to identify the Euler angles in the rotation

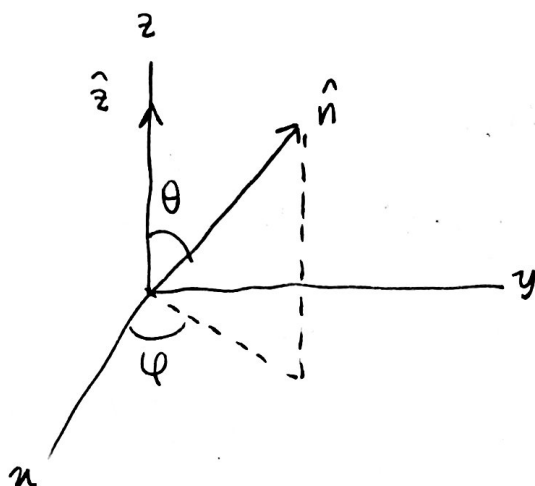
$$D'(R) J_3 D'(R)^{-1} = \vec{J} \cdot \hat{n}$$

all you need to do is get the Euler angles in the rotation

$$R \hat{z} = \hat{n}$$

(Notice that  $D(R) = D(R)^{-1}$  in the notation of the problem. This issue will be important later.)

(21)



the standard convention for the Euler angles is

$$R(\alpha, \beta, \gamma) = R_z(\alpha) R_y(\beta) R_z(\gamma)$$

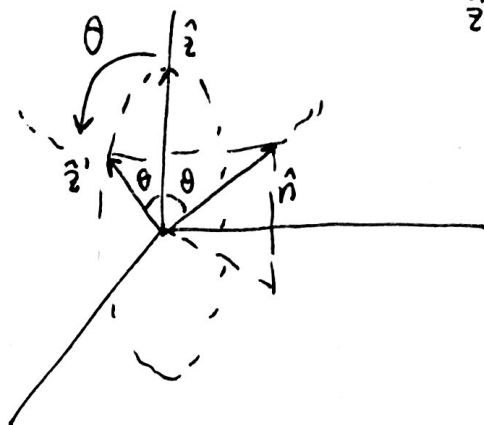
so let's do the following:

•  $R_z(\gamma) \hat{z} : \gamma = ?$

Since  $\hat{z}$  is an eigenvector of  $R_z$ , any  $\gamma$  will do. Pick  $\gamma = 0$ .

•  $R_y(\beta) R_z(0) \hat{z} : \beta = ?$

~~more~~ clearly,  $\beta = 0$ :



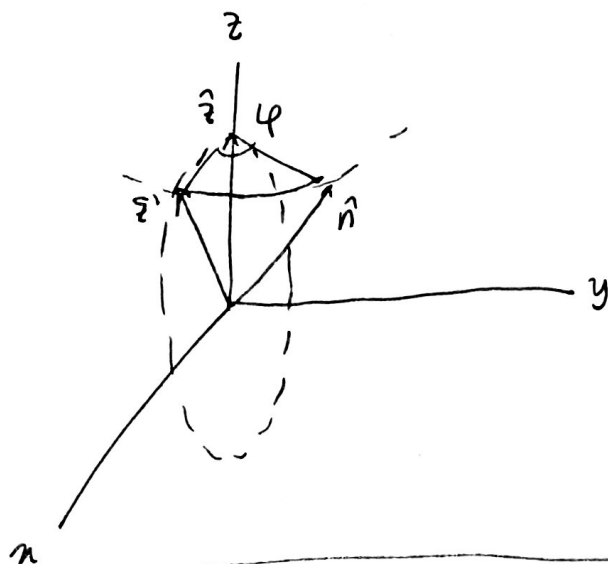
$$\hat{z}' = R_y(0) R_z(0) \hat{z}$$

(22)

• Finally,

$$R_z(\alpha) R_y(\theta) R_z(\hat{z}) = \hat{n} : \alpha = ?$$

clearly,  $\alpha = \varphi$ :



$$\therefore D(R) = D_z(\varphi) D_y(\theta) D_z(0)$$

or, since  $D(R) = D(R)^{-1}$ ,

$$D(R) = D_z(0) D_y(\theta) D_z(\varphi)$$

although this is a minor issue at the moment.

(23)

$$\begin{aligned}
(i) \quad \vec{J} \cdot \hat{n} |R, j\rangle &= D(R) J_3 D(R)^{-1} |R, j\rangle \\
&= D(R) J_3 \underbrace{D(R)^{-1} D(R)}_1 |j\rangle \\
&= D(R) J_3 |j\rangle \\
&= D(R) \hbar j |j\rangle \\
&= \hbar j D(R) |j\rangle \\
&= \hbar j |R, j\rangle \quad \text{qed}
\end{aligned}$$